

# Digital Image Processing



## Colour Image Fundamentals and Processing Techniques

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# Chapter 6

## Colour Image Fundamentals and Processing Techniques

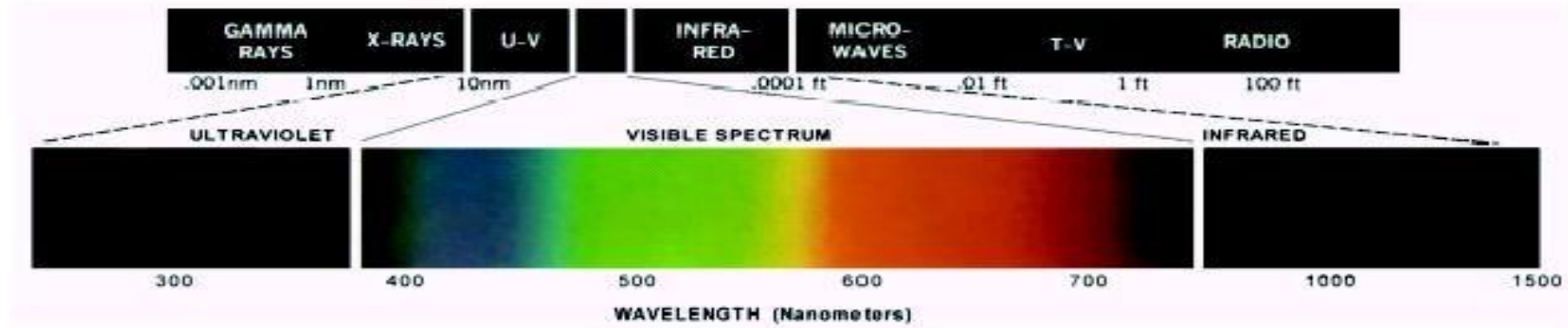


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- Colour Fundamentals
- Colour Models
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- Basics of Full-Colour Image Processing
- Colour Image Processing
- Image Smoothing and Image Sharpening
- Image Segmentation based on Colour
- Noise in Colour Images
- Colour Image Compression



# Electromagnetic Spectrum



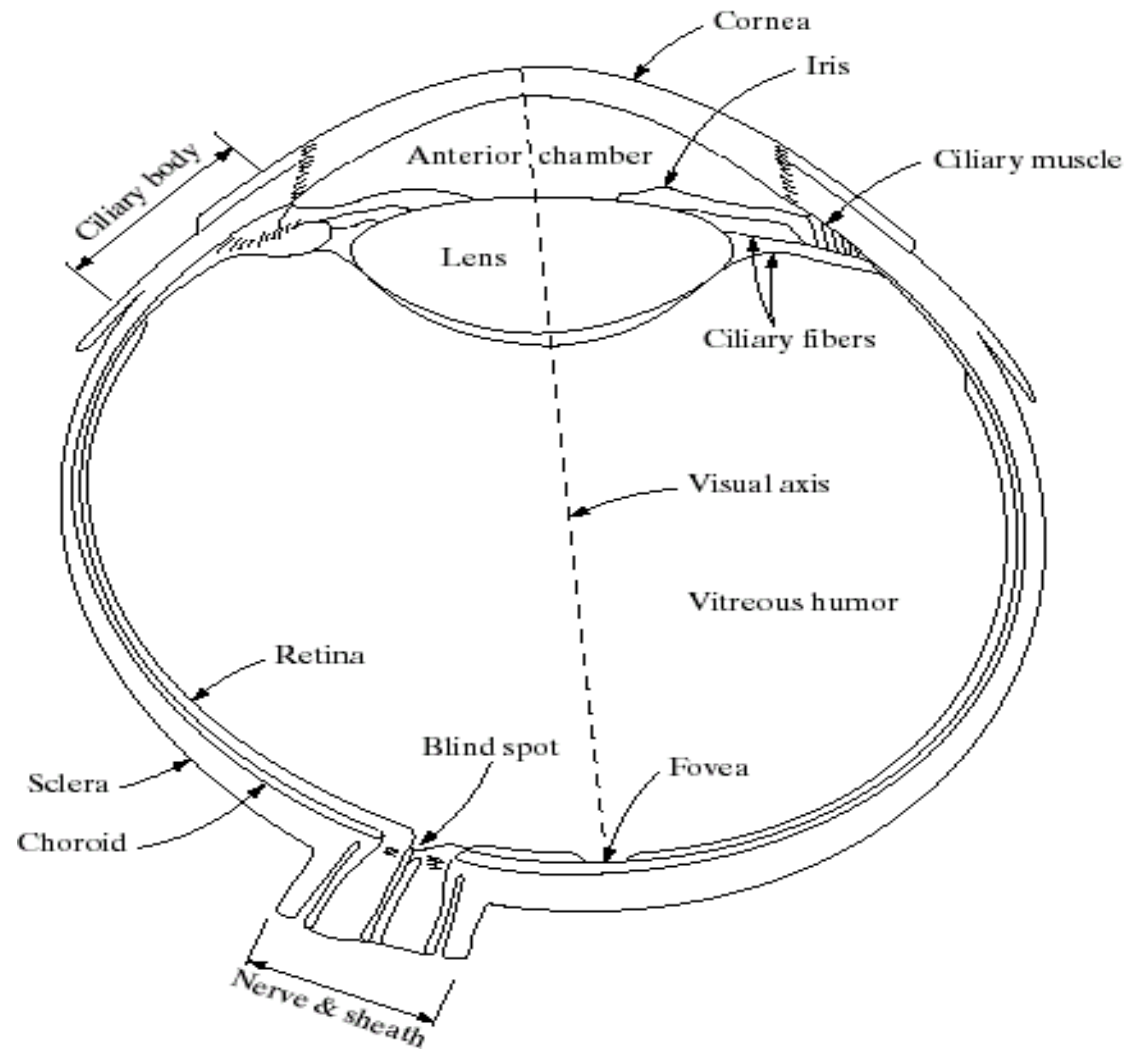
Visible light wavelength: from around 400 to 700 nm

1. For an achromatic (monochrome) light source, there is only 1 attribute to describe the quality: **intensity**

2. For a chromatic light source, there are 3 attributes to describe the quality:

**Radiance** = total amount of energy flow from a light source (Watts) **Luminance** = amount of energy received by an observer (lumens) **Brightness** = intensity

# Cross section illustration of the Human Eye



**FIGURE 2.1**  
Simplified  
diagram of a cross  
section of the  
human eye.



# Types of Photoreceptors at Retina

- Rods
  - Long and thin
  - Large quantity (~ 100 million)
  - Provide *scotopic* vision (i.e., dim light vision or at low illumination)
  - Only extract luminance information and provide a general overall picture
- Cones
  - Short and thick, densely packed in fovea (center of retina)
  - Much fewer (~ 6.5 million) and less sensitive to light than rods
  - Provide *photopic* vision (i.e., bright light vision or at high illumination)
  - Help resolve fine details as each cone is connected to its own nerve end
  - Responsible for color vision

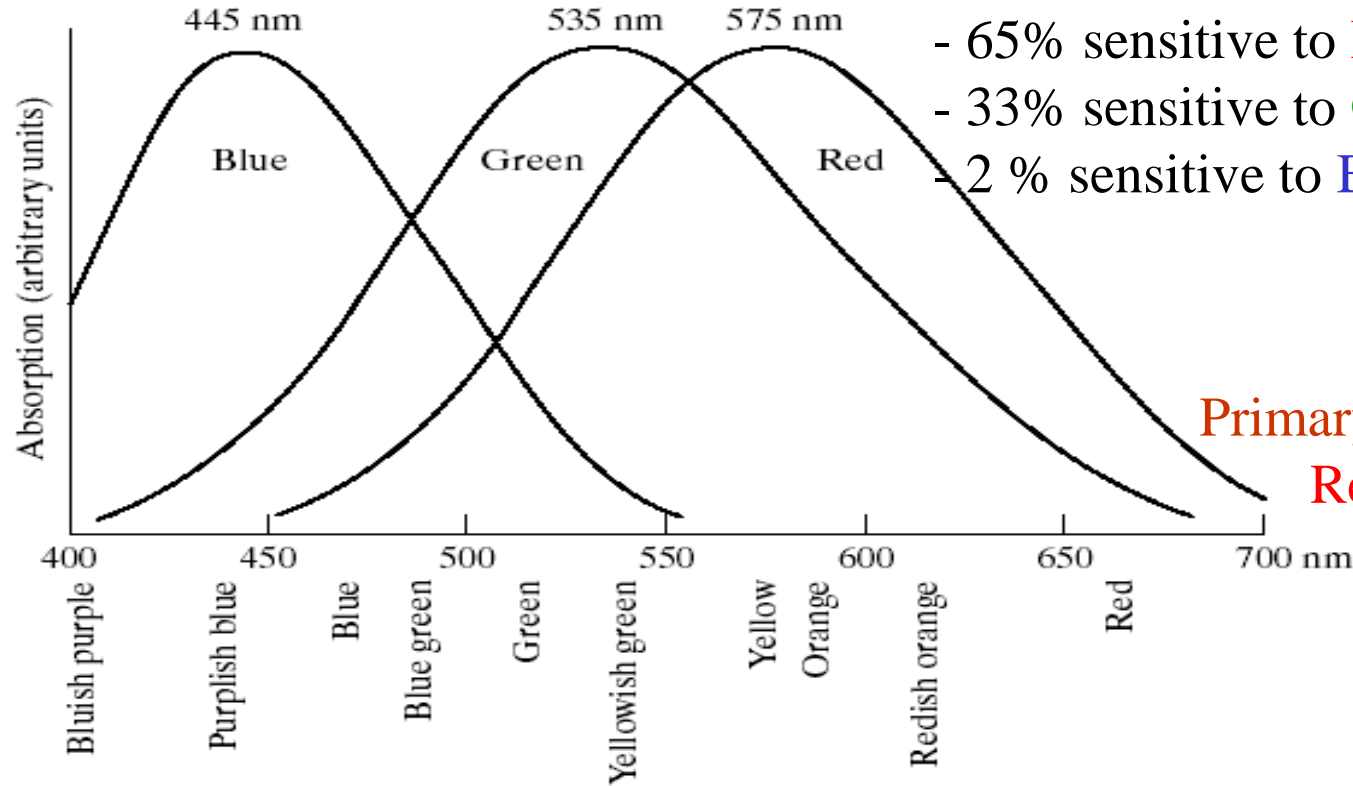
— Our Interest  
(well-lighted display)

Mesopic Vision is provided at intermediate illumination by both rod and cones

# Sensitivity of Cones in the Human Eye

7 millions cones in a human eye

- 65% sensitive to **Red light**
- 33% sensitive to **Green light**
- 2 % sensitive to **Blue light**



**Primary colors:** Defined CIE in 1931

**Red = 700 nm** **Green = 46.1nm**

**Blue = 435.8 nm**

CIE = Commission Internationale de l'Eclairage (The International Commission on Illumination)

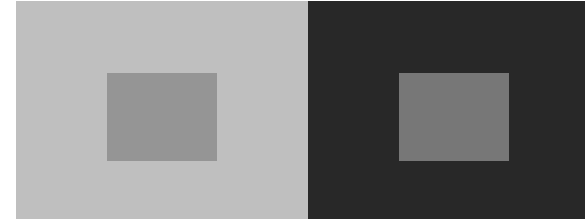


# Luminance vs. Brightness

Same lum.  
Different  
brightness



Different lum.  
Similar brightness



- Luminance (or intensity)
  - Independent of the luminance of surroundings

$$L(x, y) = \int_0^{inf} I(x, y, \lambda) V(\lambda) d\lambda$$

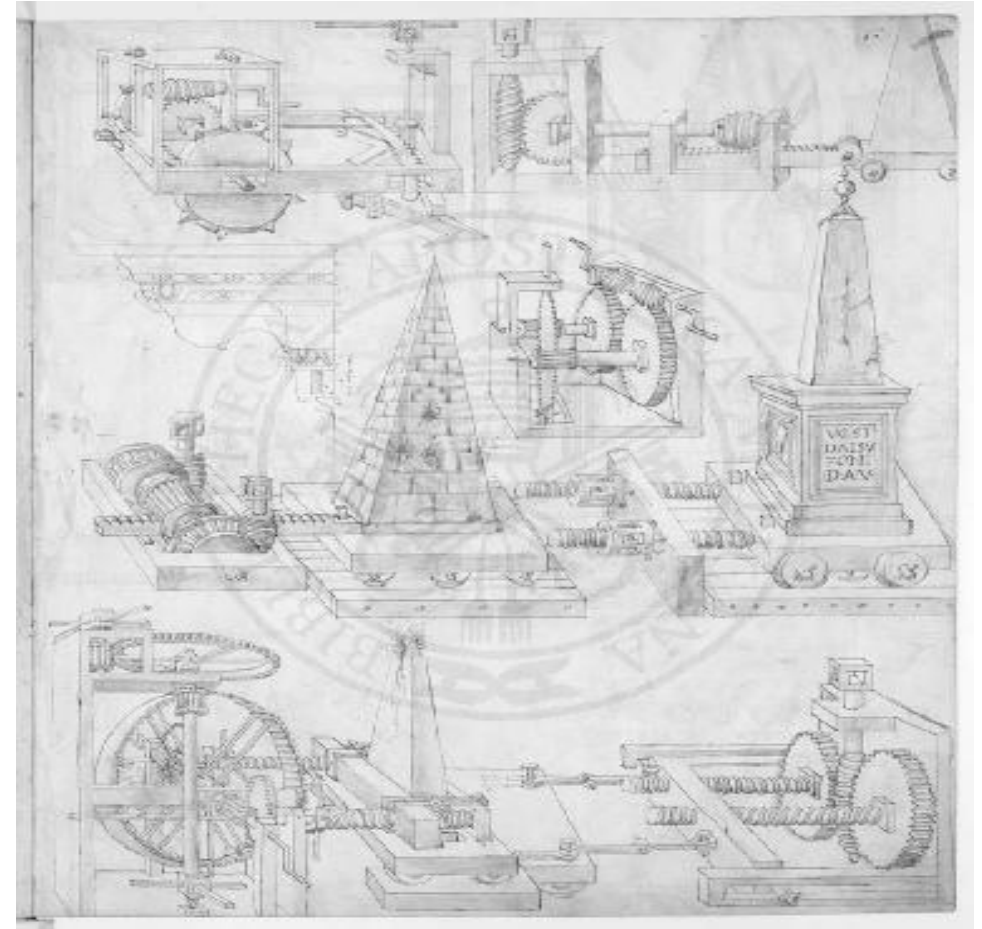
$I(x, y, \lambda)$  -- spatial light distribution

$V(\lambda)$  -- relative luminous efficiency func. of visual system ~ bell shape (different for scotopic vs. photopic vision; highest for green wavelength, second for red, and least for blue )

- Brightness
  - Perceived luminance
  - Depends on surrounding luminance

# Luminance vs. Brightness (cont'd)

- Example: visible digital watermark
  - How to make the watermark appear at the same graylevel all over the image?

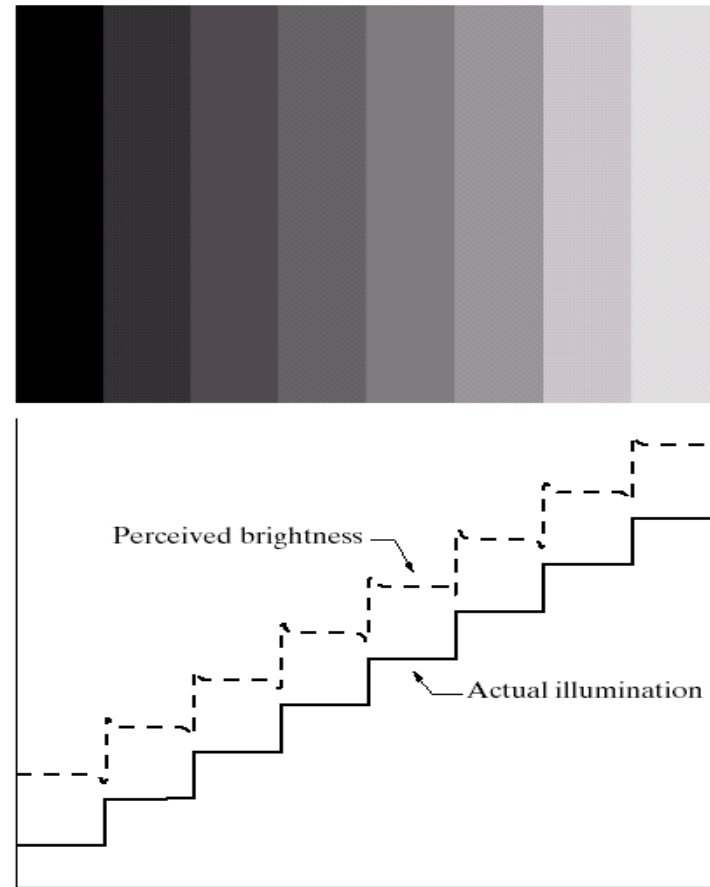


from IBM Watson web page "Vatican Digital Library"



# Look into Simultaneous Contrast Phenomenon

- Human perception more sensitive to luminance contrast than absolute luminance
- Weber's Law:  $|L_s - L_0| / L_0 = \text{const}$ 
  - Luminance of an object ( $L_0$ ) is set to be just noticeable from luminance of surround ( $L_s$ )
  - For just-noticeable luminance difference  $\Delta L$ :
$$\Delta L / L \approx d(\log L) \approx 0.02 (\text{const})$$
    - equal increments in log luminance are perceived as equally different
- Empirical luminance-to-contrast models
  - Assume  $L \in [1, 100]$ , and  $c \in [0, 100]$
  - $c = 50 \log_{10} L$  (logarithmic law, widely used)
  - $c = 21.9 L^{1/3}$  (cubic root law)



a  
b

**FIGURE 2.7**  
 (a) An example showing that perceived brightness is not a simple function of intensity. The relative vertical positions between the two profiles in (b) have no special significance; they were chosen for clarity.

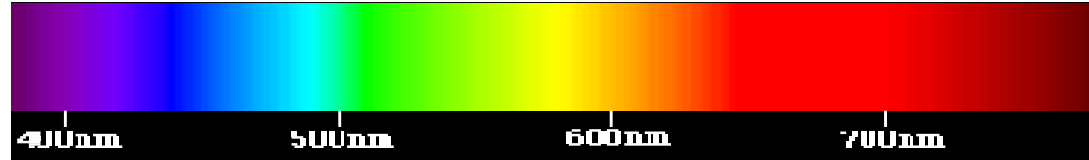
Figure is from slides at Gonzalez/Woods DIP book website (Chapter 2)

- Visual system tends to undershoot or overshoot around the boundary of regions of different intensities
- Demonstrates the perceived brightness is not a simple function of light intensity



# Color of Light

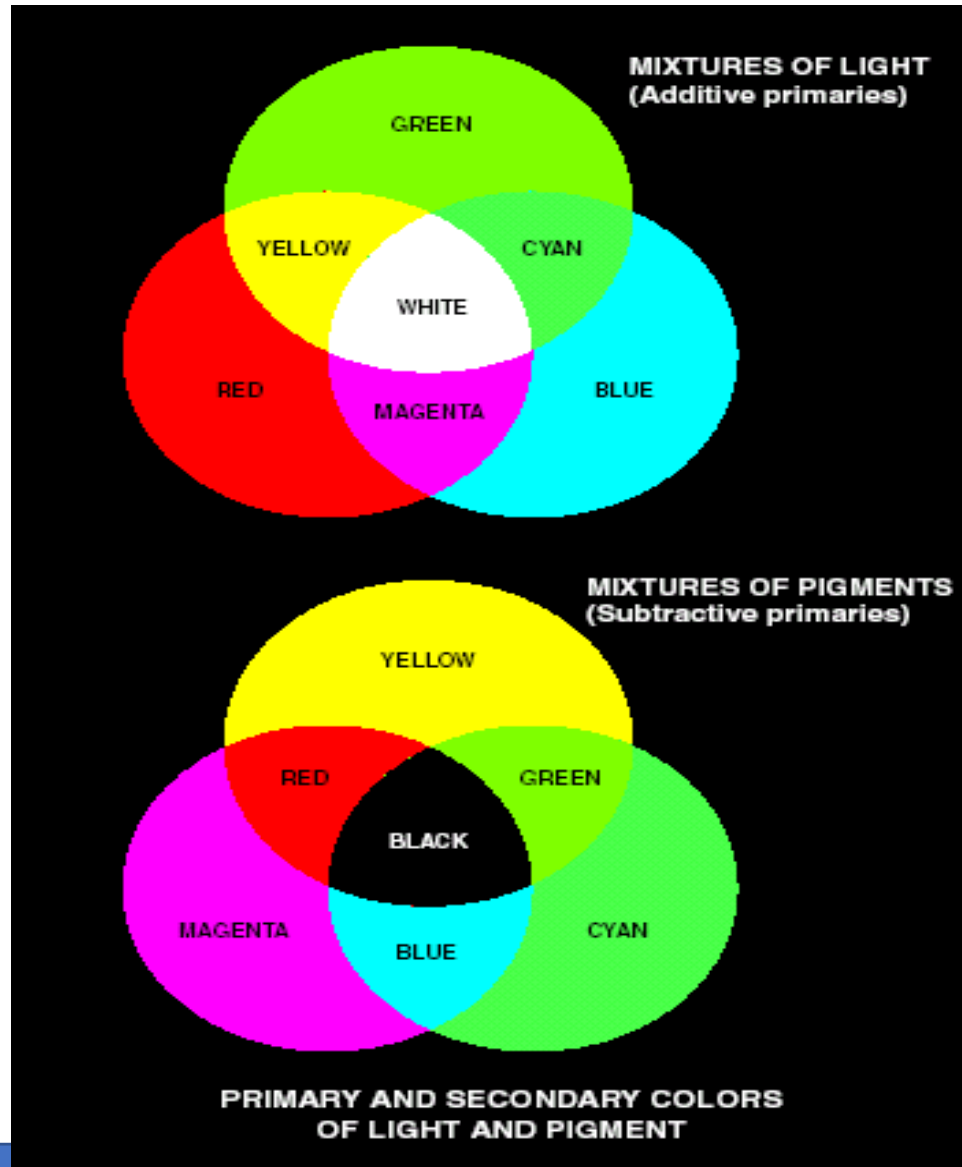
- Perceived color depends on spectral content (wavelength composition)
  - e.g., 700nm ~ red.
  - “spectral color”
    - A light with very narrow bandwidth



“Spectrum” from <http://www.physics.sfasu.edu/astro/color.html>

- A light with equal energy in all visible bands appears white

# Primary and Secondary Colors



Additive primary colors: RGB used in the case of light sources such as colour monitors

RGB add together to get white

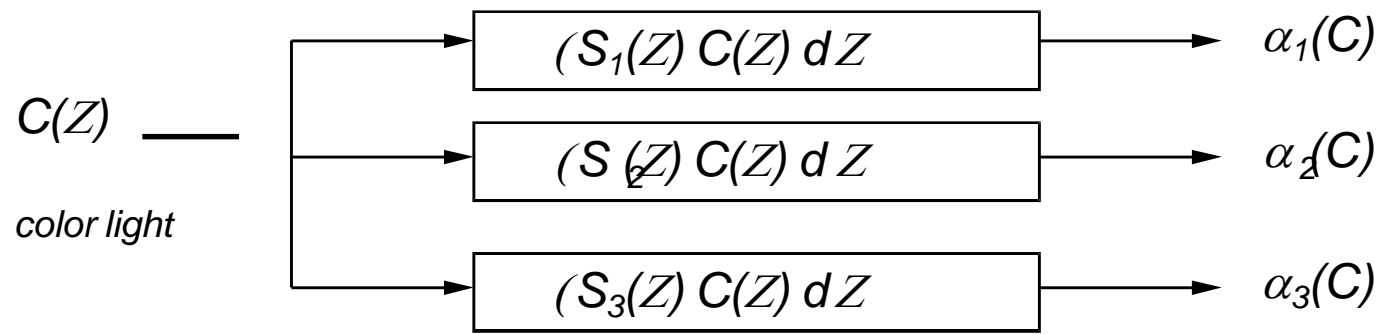
Subtractive primary colors: CMY use in the case of pigments in printing devices

White subtracted by CMY to get Black



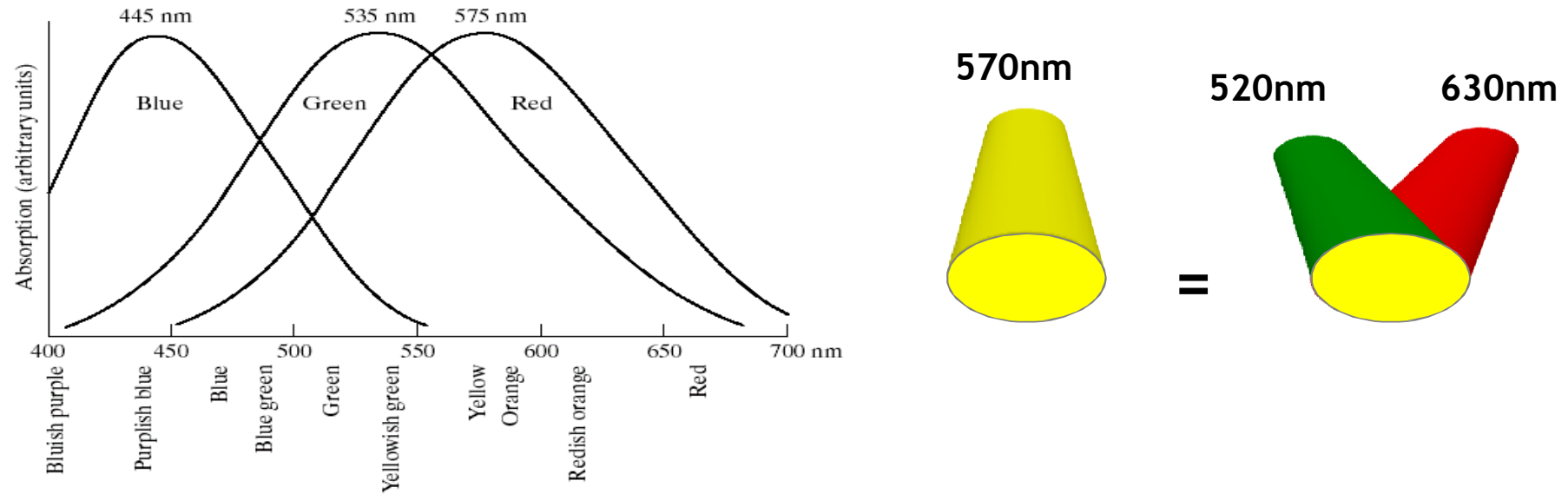
# Representation by Three Primary Colors

- Any color can be reproduced by mixing an appropriate set of three primary colors  
(Thomas Young, 1802)
- Three types of cones in human retina
  - Absorption response  $S_i(Z)$  has peaks around 450nm (blue), 550nm (green), 620nm (yellow-green)
  - Color sensation depends on the spectral response  $\{ \alpha_1(C), \alpha_2(C), \alpha_3(C) \}$  rather than the complete light spectrum  $C(Z)$



Identically perceived colors if  $\alpha_i(C_1) = \alpha_i(C_2)$

# Example: Seeing Yellow Without Yellow



**FIGURE 6.3** Absorption of light by the red, green, and blue cones in the human eye as a function of wavelength.

Green and red light are mixed to obtain perception of yellow, without shining a single yellow photon

“Seeing Yellow” figure is from B.Liu ELE330 S’01 lecture notes @ Princeton; R/G/B cone response is from slides at Gonzalez/ Woods DIP book website



# Color Matching and Reproduction

- Mixture of three primaries:  $C = \text{Sum}(\int_k P_k(Z))$
- To match a given color  $C_1$ 
  - adjust  $\int_k$  such that  $\alpha_i(C_1) = \alpha_i(C)$ ,  $i = 1, 2, 3$ .
- Tristimulus values  $T_k(C)$ 
  - $T_k(C) = \int_k / w_k$   
 *$w_k$  – the amount of  $k^{\text{th}}$  primary to match the reference white*
- Chromaticity  $t_k = T_k / (T_1 + T_2 + T_3)$ 
  - $t_1 + t_2 + t_3 = 1$
  - visualize  $(t_1, t_2)$  to obtain chromaticity diagram



# Color Characterization

Hue: Dominant color corresponding to a dominant wavelength of mixture light wave

Saturation: Relative purity or amount of white light mixed with a hue (inversely proportional to amount of white light added)

Intensity

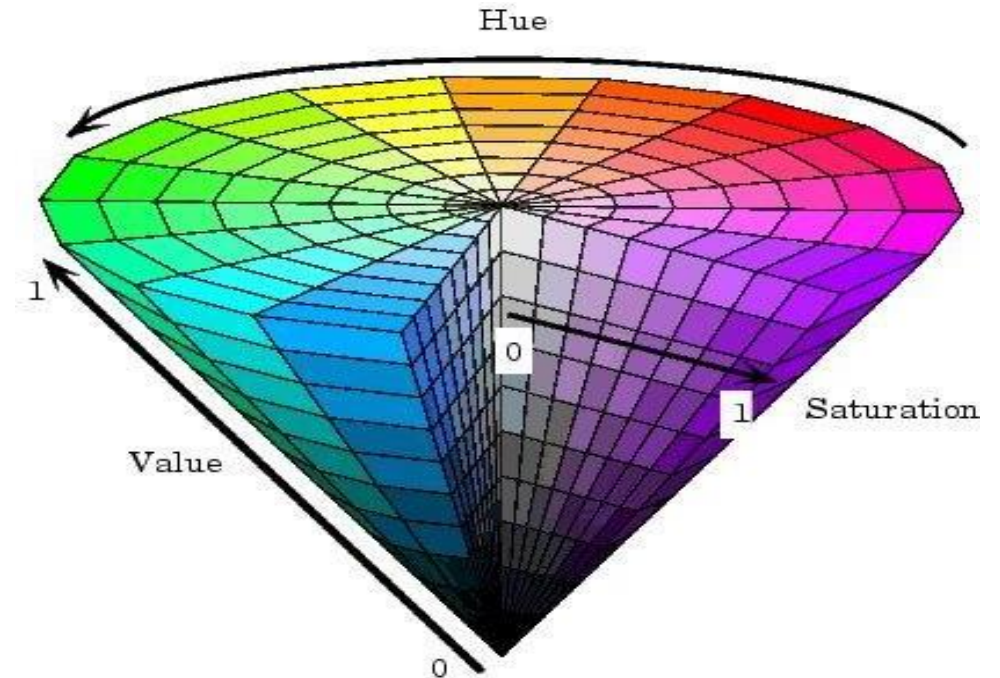
Brightness

Hue Saturation } Chromaticity

amount of red (X), green (Y) and blue (Z) to form any particular color is called *tristimulus*.

# Perceptual Attributes of Color

- Value of Brightness (perceived luminance)
- Chrominance
  - **Hue**
    - specify color tone (redness, greenness, etc.)
    - depend on peak wavelength
  - **Saturation**
    - describe how pure the color is
    - depend on the spread (bandwidth) of light spectrum
    - reflect how much white light is added

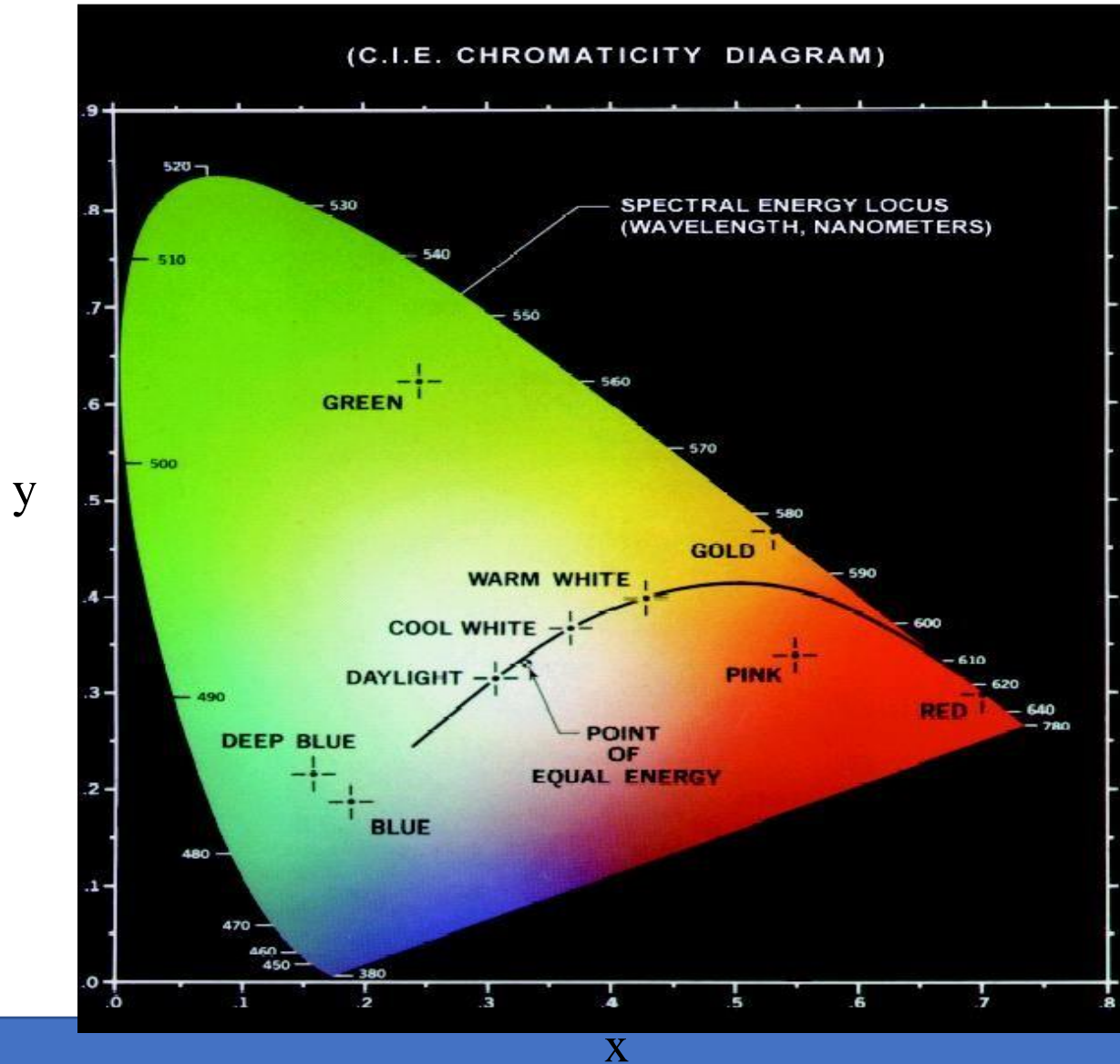


HSV circular cone is from online documentation of Matlab image processing toolbox

[http://www.mathworks.com/access/helpdesk/help/toolbox/images/col\\_or10.shtml](http://www.mathworks.com/access/helpdesk/help/toolbox/images/col_or10.shtml)

- RGB  $\square$  HSV Conversion~ *nonlinear*

# CIE Chromaticity Diagram



Trichromatic coefficients:

$$x = \frac{X}{X + Y + Z}$$

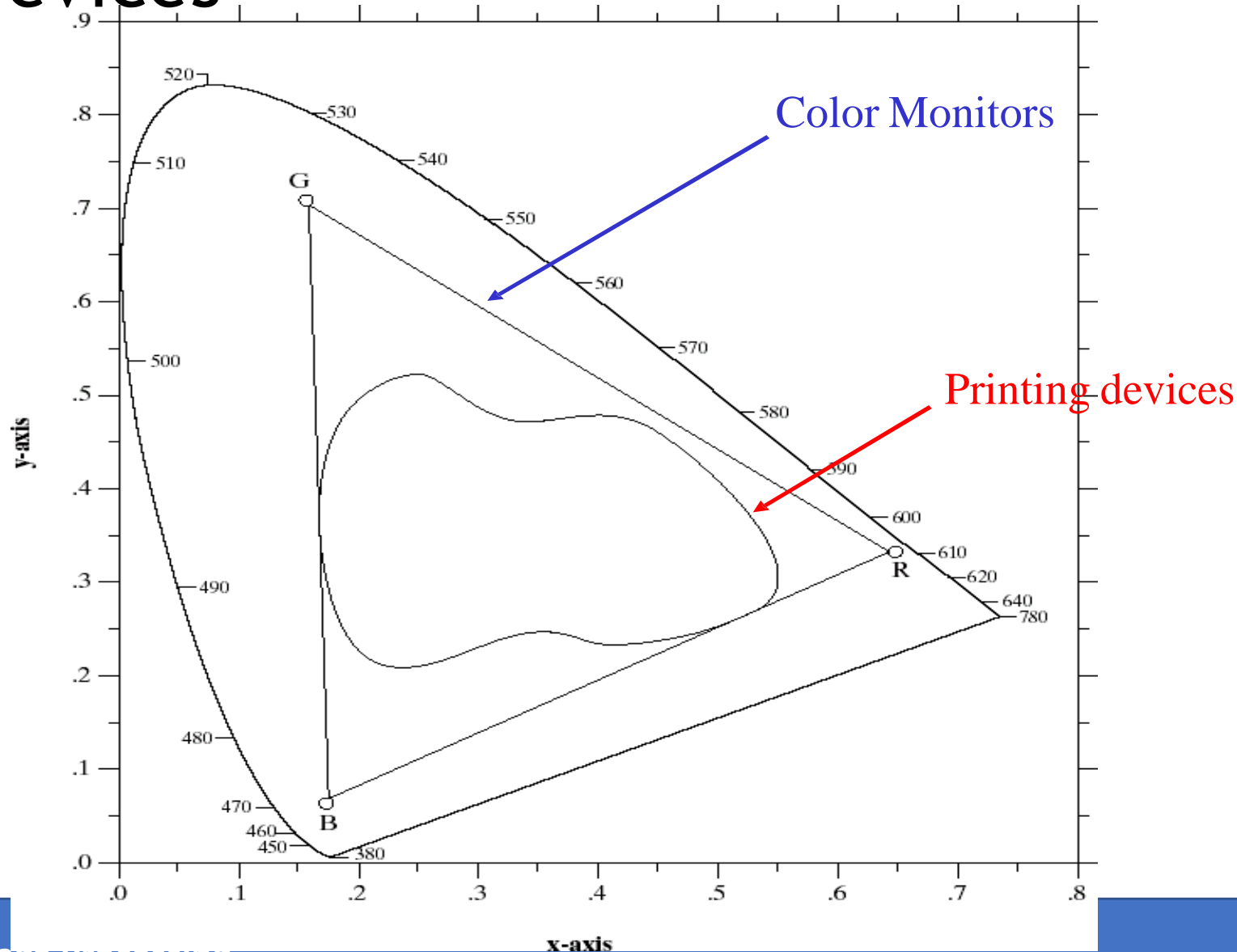
$$y = \frac{Y}{X + Y + Z}$$

$$z = \frac{Z}{X + Y + Z}$$

$$x + y + z = 1$$

Points on the boundary are fully saturated colors

# Color Gamut of Color Monitors and Printing Devices



# CIE Color Coordinates (cont'd)

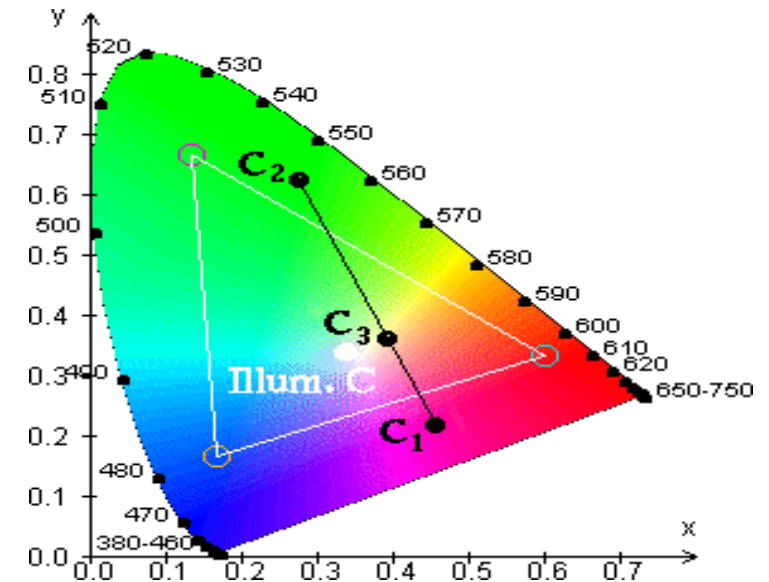
- CIE XYZ system

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = \begin{bmatrix} 0.490 & 0.310 & 0.200 \\ 0.177 & 0.813 & 0.011 \\ 0.000 & 0.010 & 0.990 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

- hypothetical primary sources to yield all-positive spectral tristimulus values
- Y ~ luminance

- Color gamut of 3 primaries

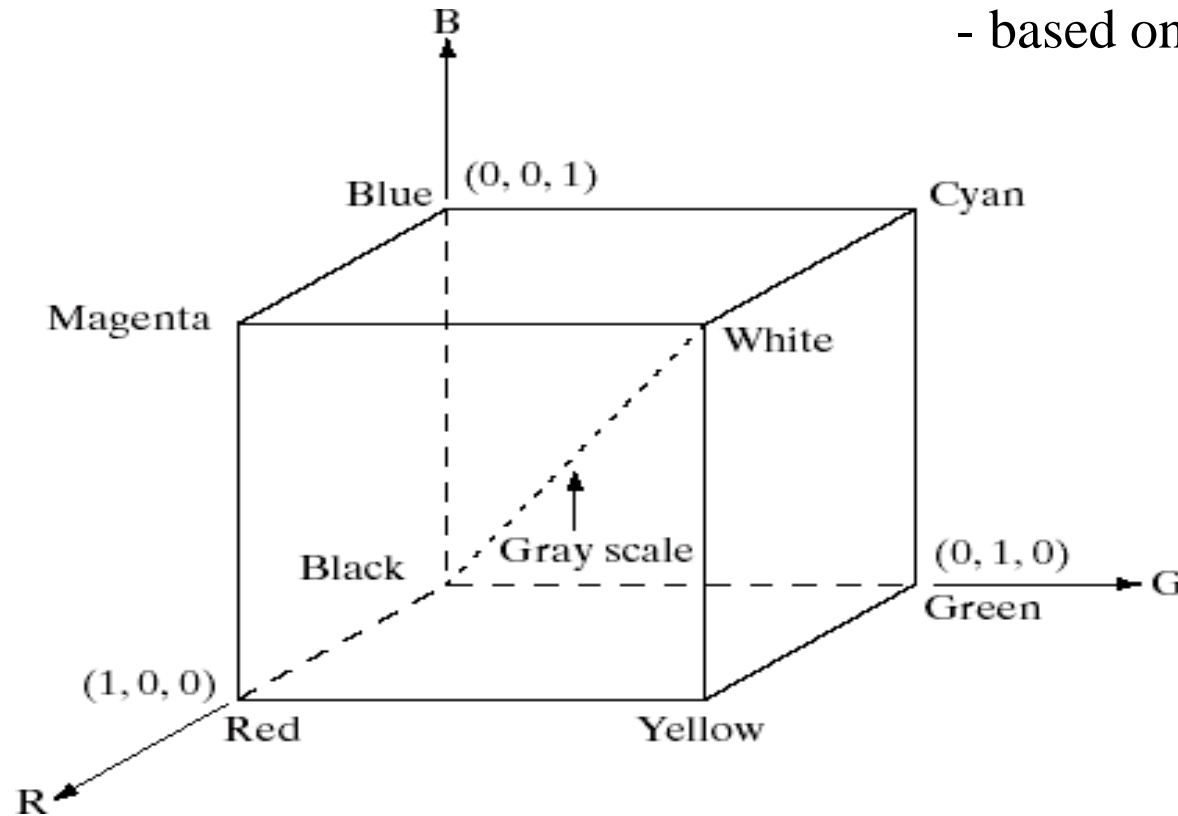
- Colors on line C1 and C2 can be produced by linear mixture of the two
- Colors inside the triangle gamut can be reproduced by three primaries



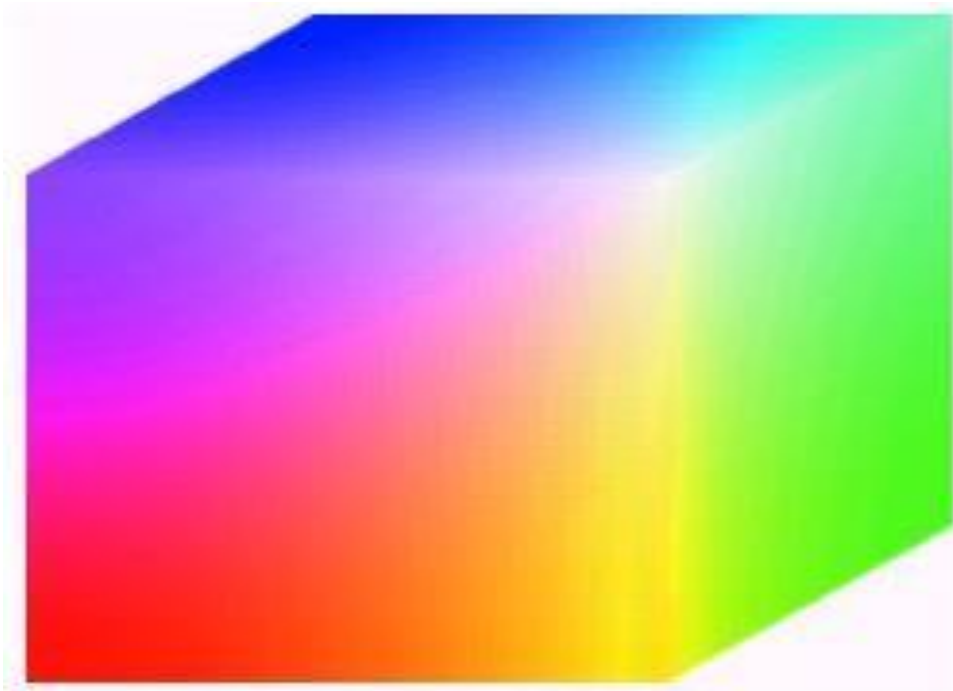
# RGB Color Model

Purpose of color models: to facilitate the specification of colors in some standard

RGB color models:  
- based on cartesian coordinate system

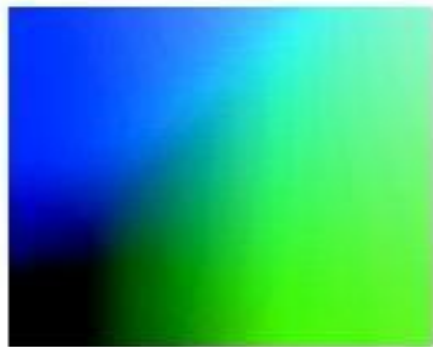


# RGB Color Cube



R = 8 bits  
8 bits G = 8  
bits B = 8

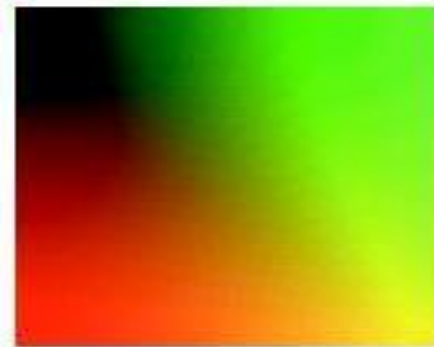
Color depth 24 bits  
= 16777216 colors



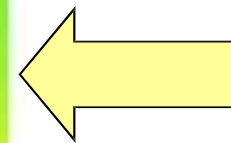
(R = 0)



(G = 0)

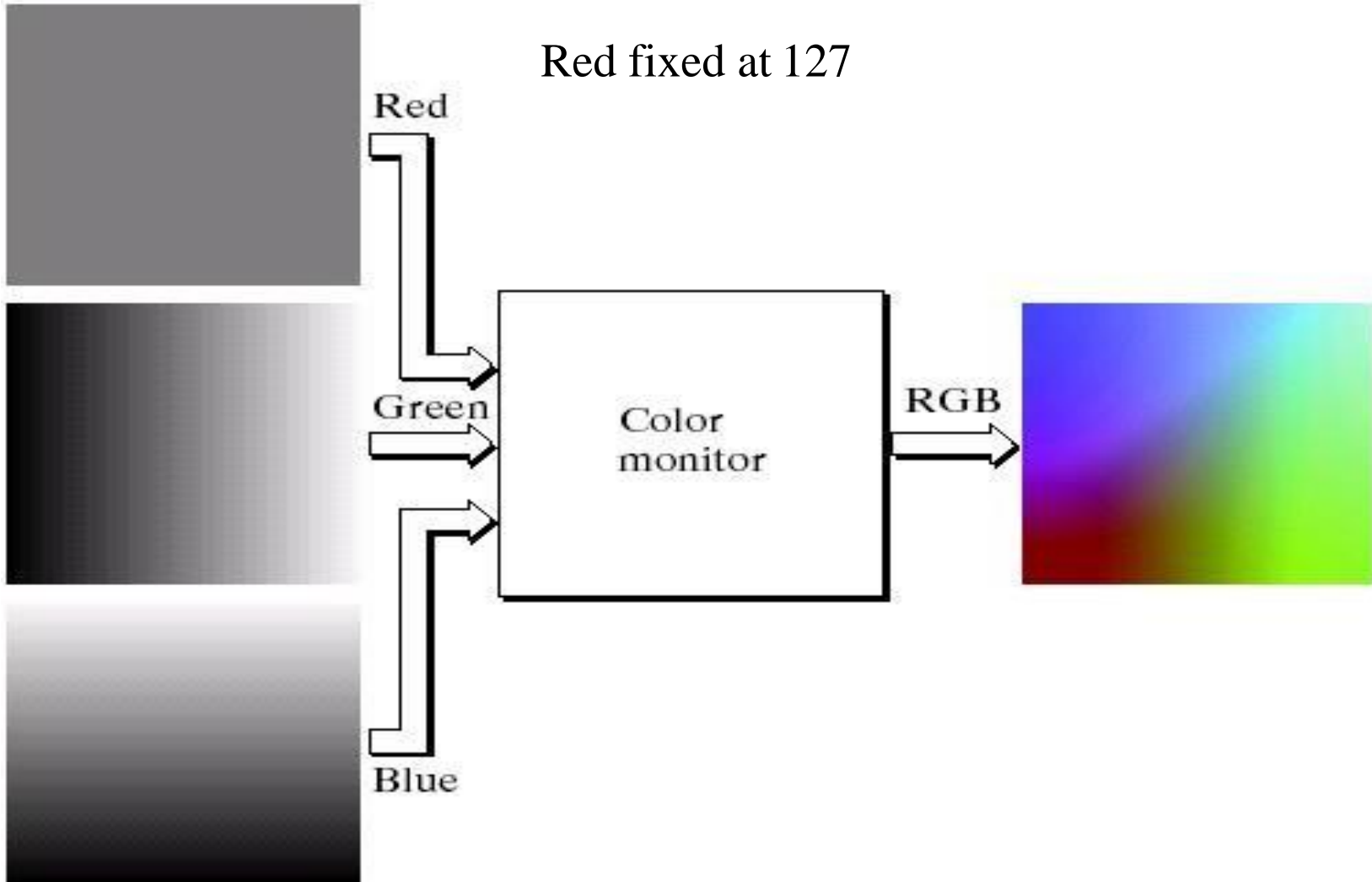


(B = 0)



Hidden faces of  
the cube

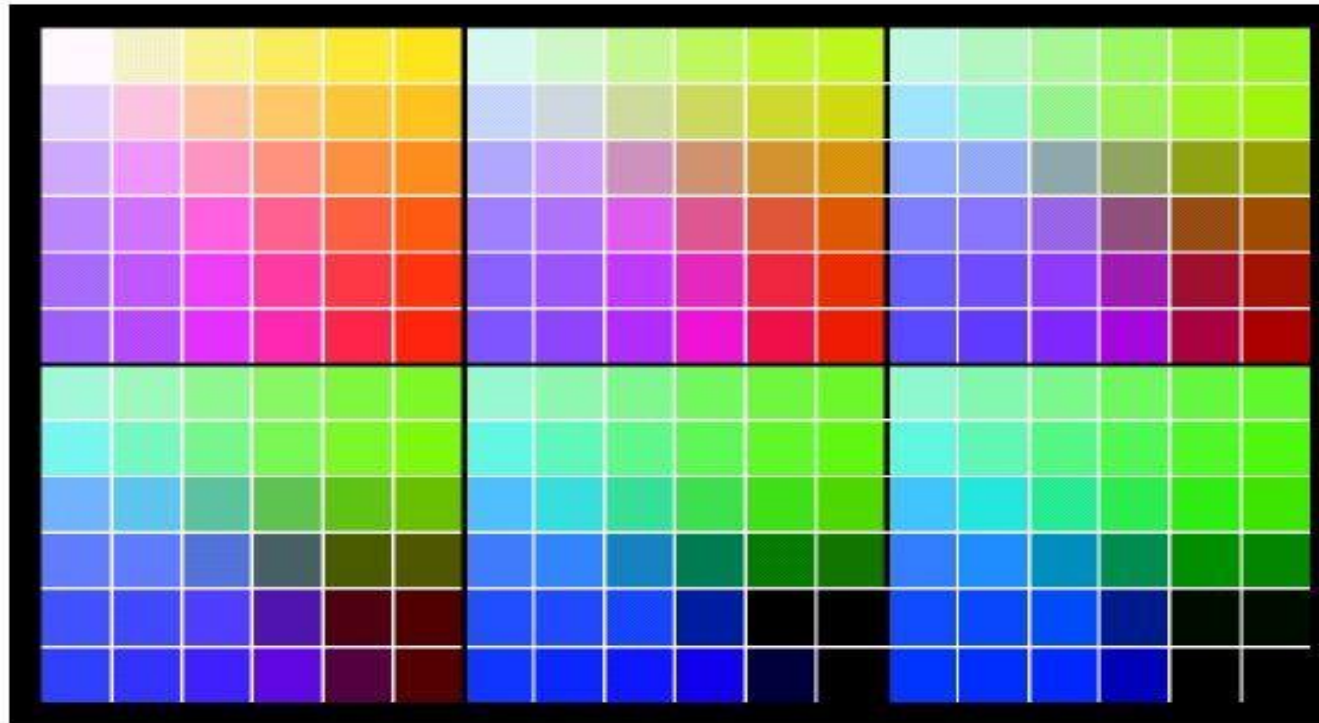
# RGB Color Model



# Safe RGB Colors

Safe RGB colors: a subset of RGB colors.

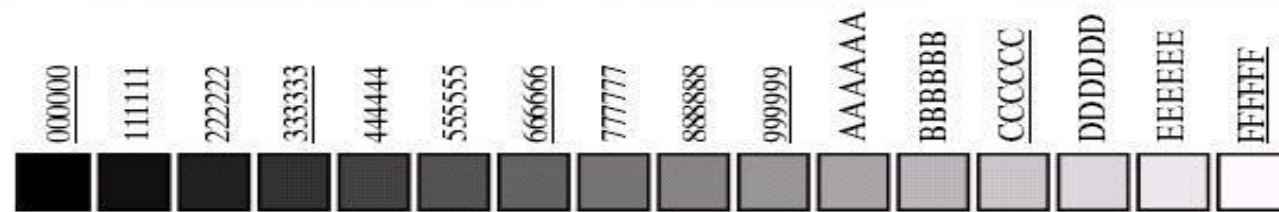
There are 216 colors common in most operating systems.



a  
b

**FIGURE 6.10**

(a) The 216 safe RGB colors.  
 (b) All the grays in the 256-color RGB system (grays that are part of the safe color group are shown underlined).

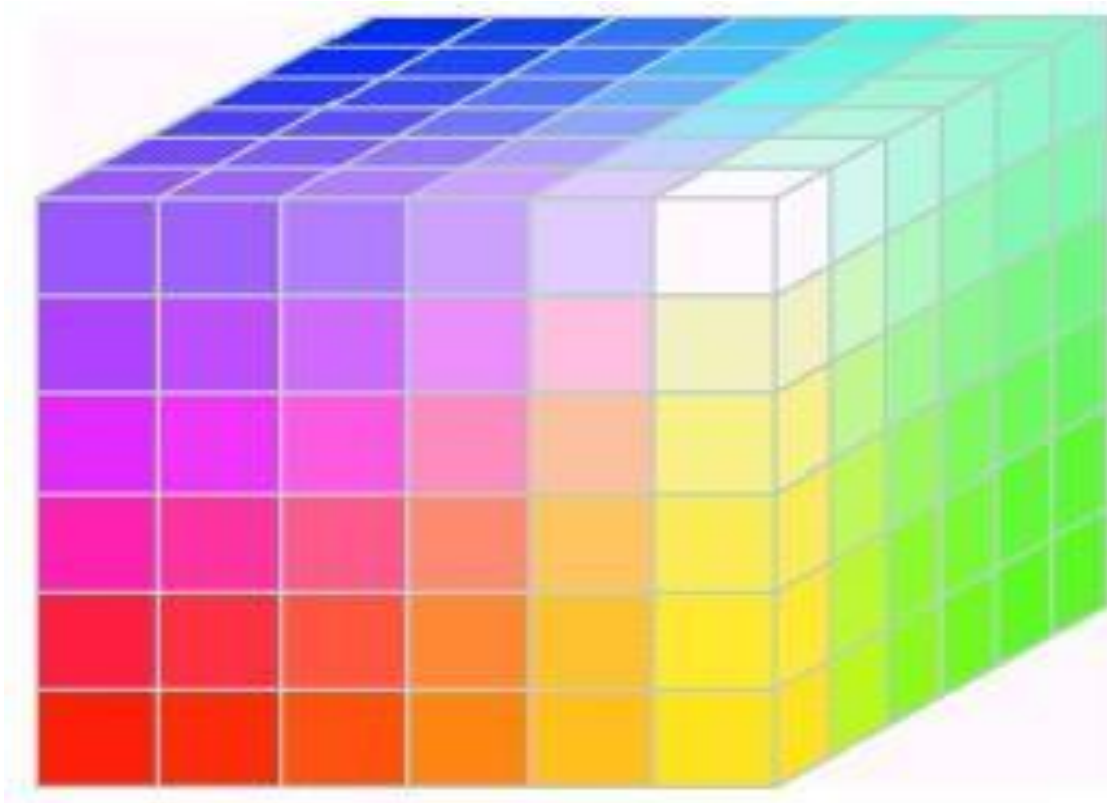


# RGB Safe-color Cube

Number System		Color Equivalents					
Hex	00	33	66	99	CC	FF	
Decimal	0	51	102	153	204	255	

**TABLE 6.1**

Valid values of each RGB component in a safe color.



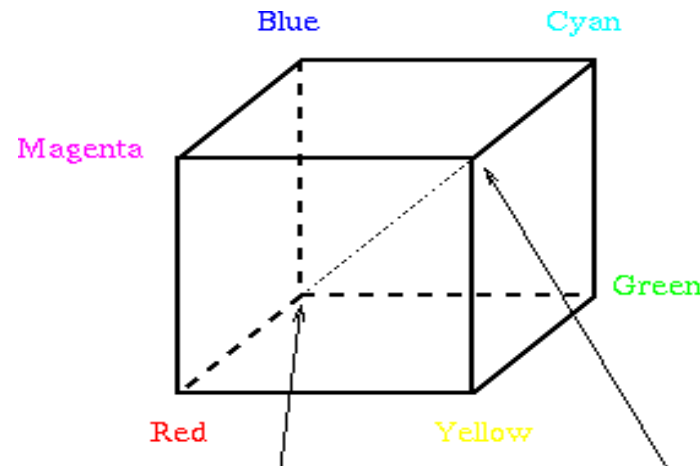
The RGB Cube is divided into 6 intervals on each axis to achieve the total  $6^3 = 216$  common colors.

However, for 8 bit color representation, there are the total 256 colors. Therefore, the remaining 40 colors are left to OS.

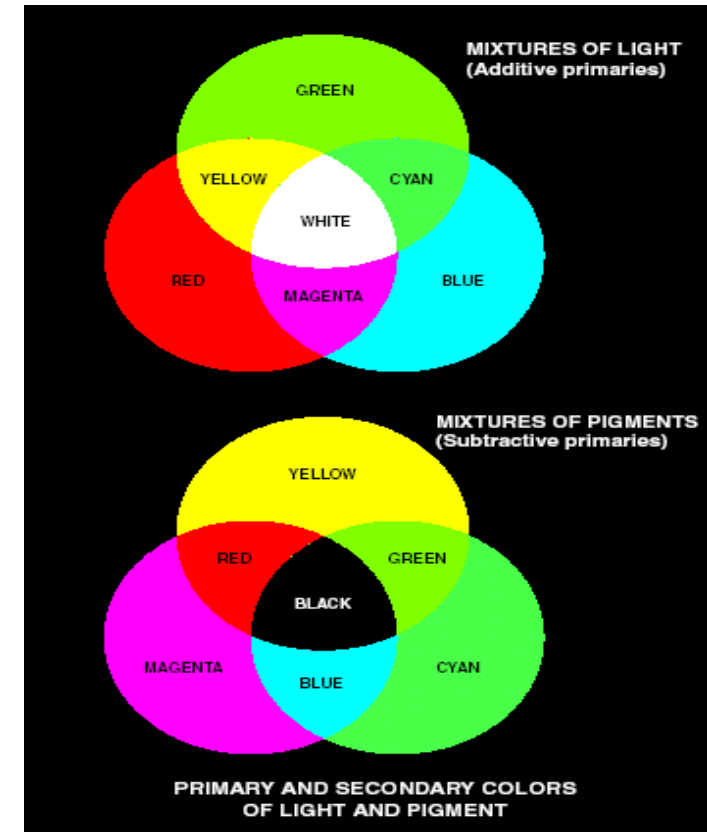
# CMY and CMYK Color Models

- Primary colors for pigment
  - Defined as one that subtracts/absorbs a primary color of light & reflects the other two
- CMY – Cyan, Magenta, Yellow
  - Complementary to RGB
  - Proper mix of them produces black

C=Cyan M = Magenta  
Y = Yellow K = Black



$$\begin{bmatrix} C \\ M \\ Y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$





# HSI Color Model

RGB, CMY models are not good for human interpreting

## HSI Color model:

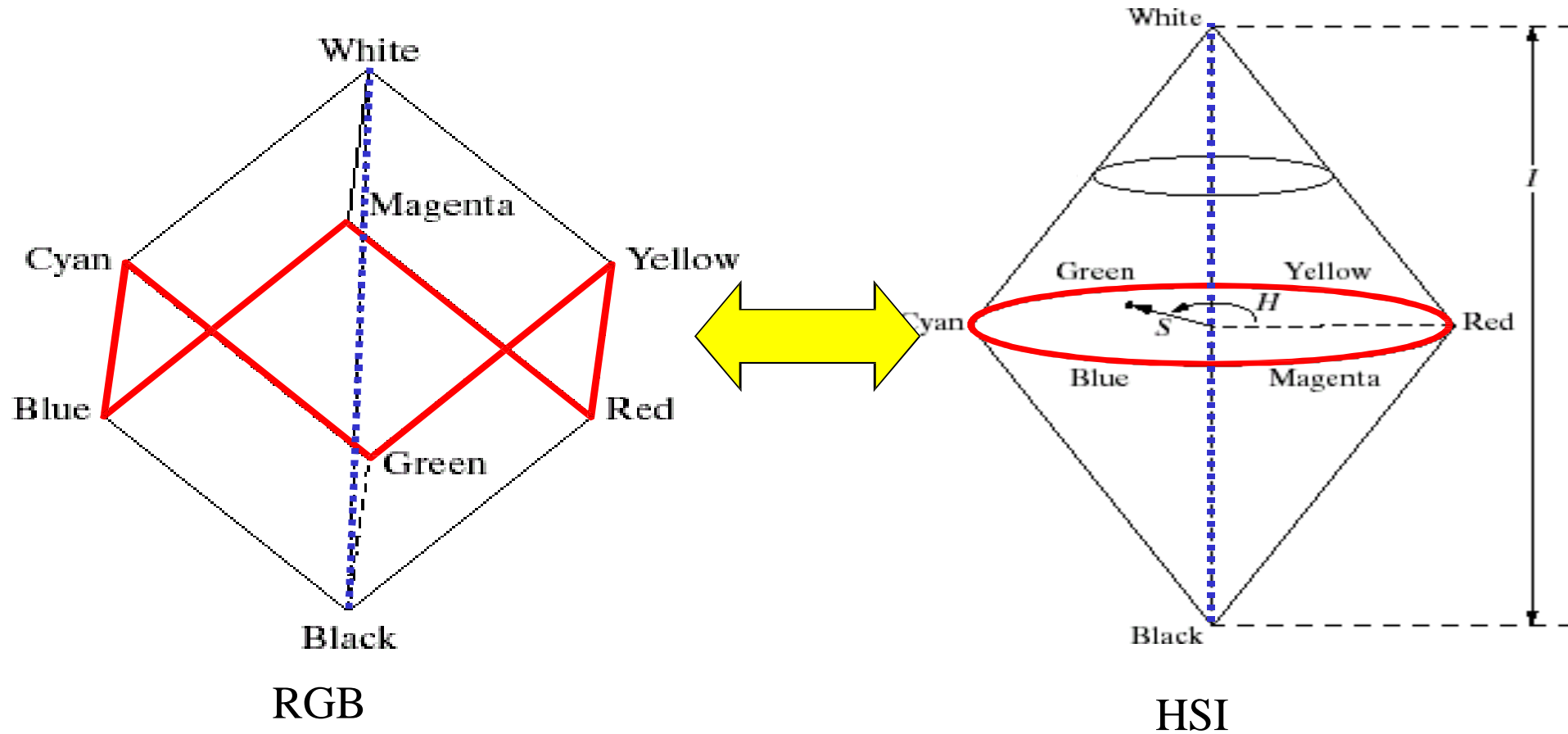
Hue: Dominant color

Saturation: Relative purity (inversely proportional to amount of white light added)

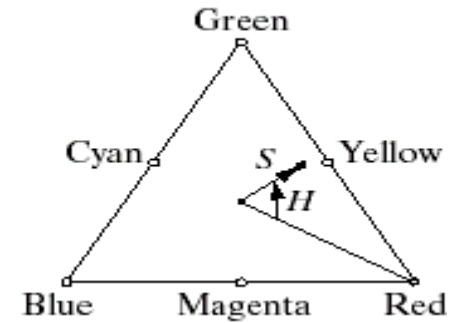
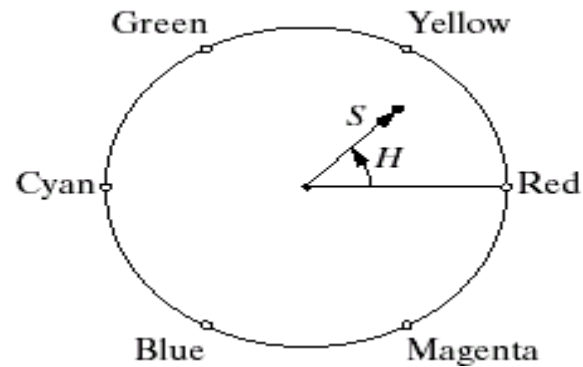
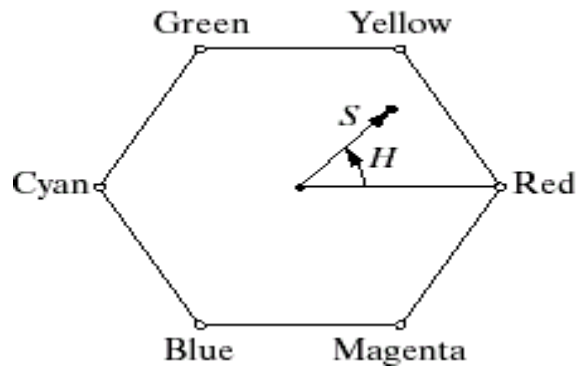
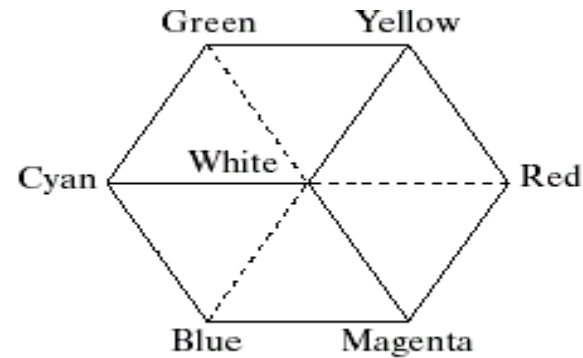
Intensity: Brightness

} Color carrying information

# Relationship Between RGB and HSI Color Models

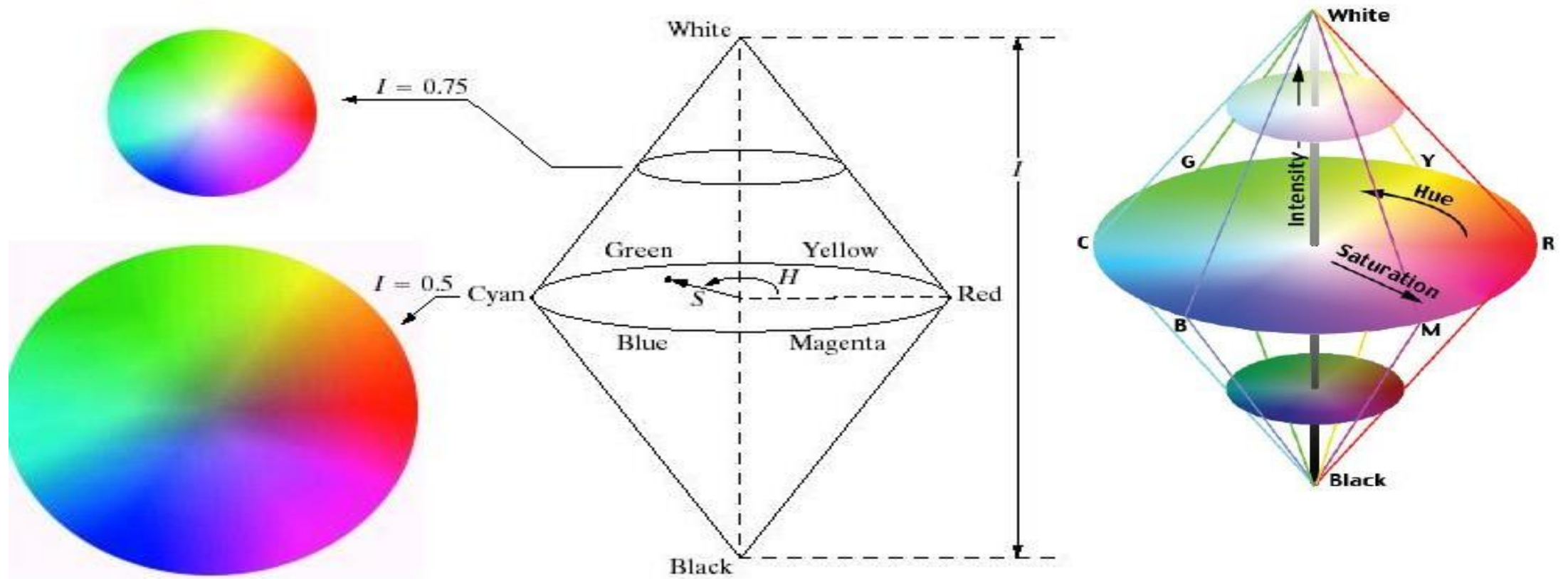


# Hue and Saturation on Color Planes



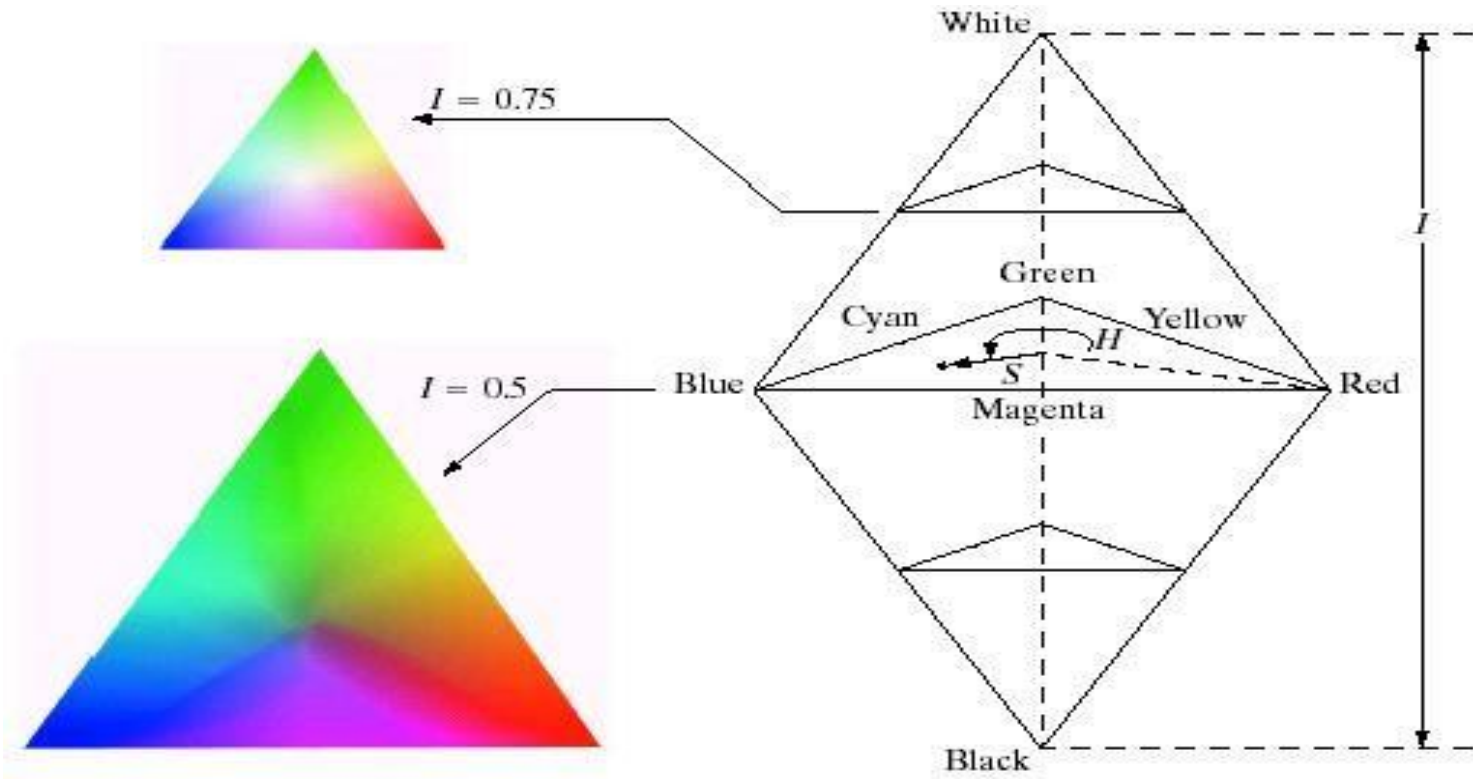
1. A dot in the plane is an arbitrary color
2. Hue is an angle from a red axis.
3. Saturation is a distance to the point.

# HSI Color Model (cont.)



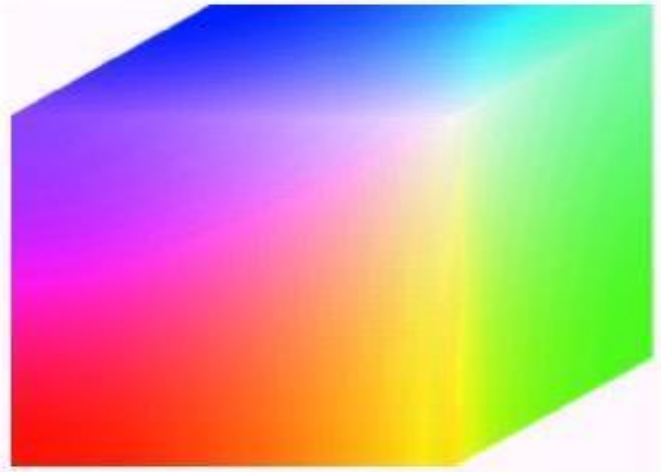
Intensity is given by a position on the vertical axis.

# HSI Color Model

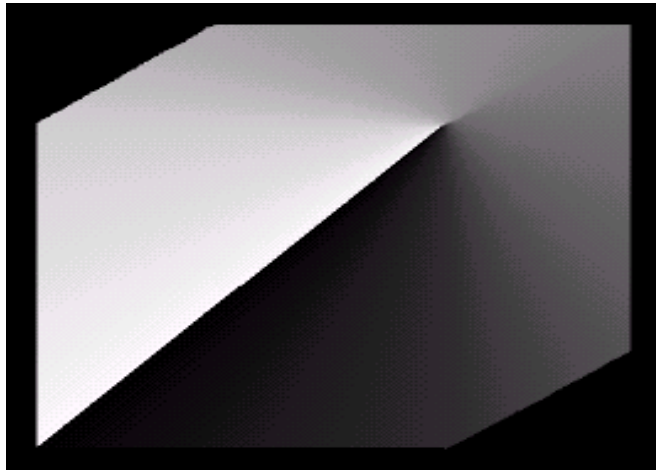


Intensity is given by a position on the vertical axis.

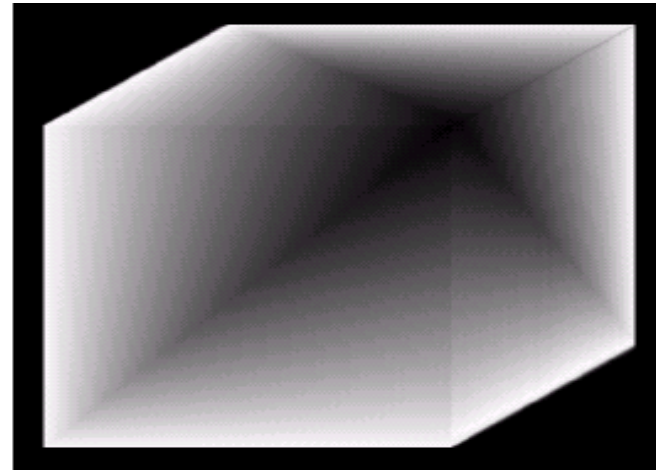
# Example: HSI Components of RGB Cube



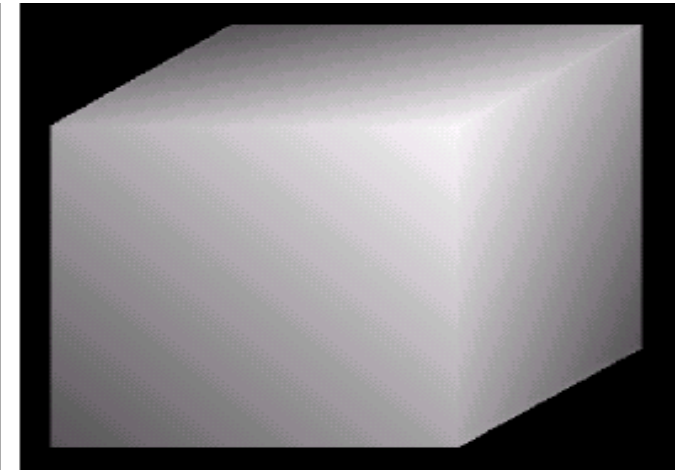
RGB Cube



Hue



Saturation





# Converting Colors from RGB to HSI

$$H = \begin{cases} \gamma & \text{if } B \leq G \\ 360 - \gamma & \text{if } B > G \end{cases}$$

$$\gamma = \cos^{-1} \left[ \frac{1/2 \{ (R - G) + (R - B) \}}{[ (R - G)^2 + (R - B)(G - B) ]^{1/2}} \right]$$

$$S = 1 - \frac{3}{R + G + B}$$

$$I = \frac{1}{3} (R + G + B)$$



# Converting Colors from HSI to RGB

RG sector:  $0 \leq H < 120$

GB sector:  $120 \leq H < 240$

$$R = I \left[ 1 + \frac{S \cos H}{\cos(60^\circ - H)} \right]$$

$$B = I(1 - S)$$

$$G = 1 - (R + B)$$

BR sector:  $240 \leq H \leq 360$

$$H = H - 240$$

$$B = I \left[ 1 + \frac{S \cos H}{\cos(60^\circ - H)} \right]$$

$$G = I(1 - S)$$

$$R = 1 - (G + B)$$

$$H = H - 120$$

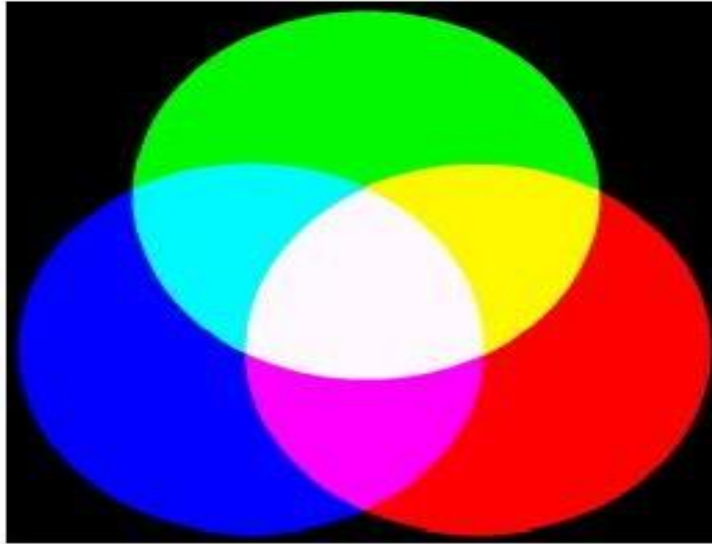
$$R = I(1 - S)$$

$$G = I \left[ 1 + \frac{S \cos H}{\cos(60^\circ - H)} \right]$$

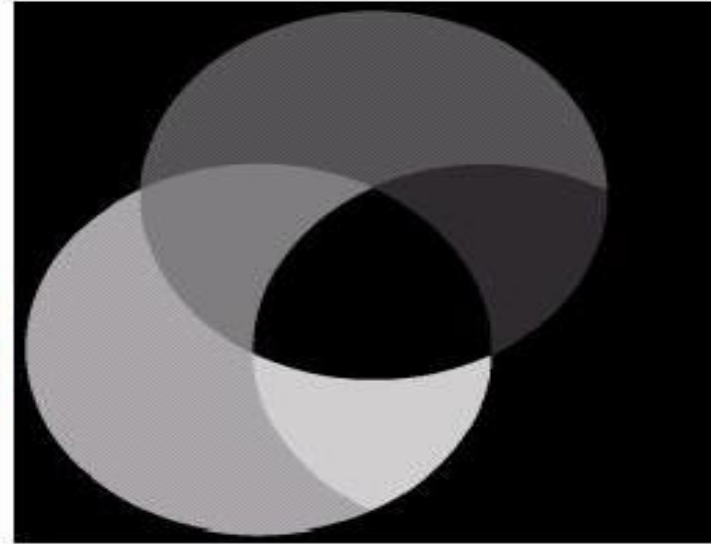
$$B = 1 - (R + G)$$

# Example: HSI Components of RGB Colors

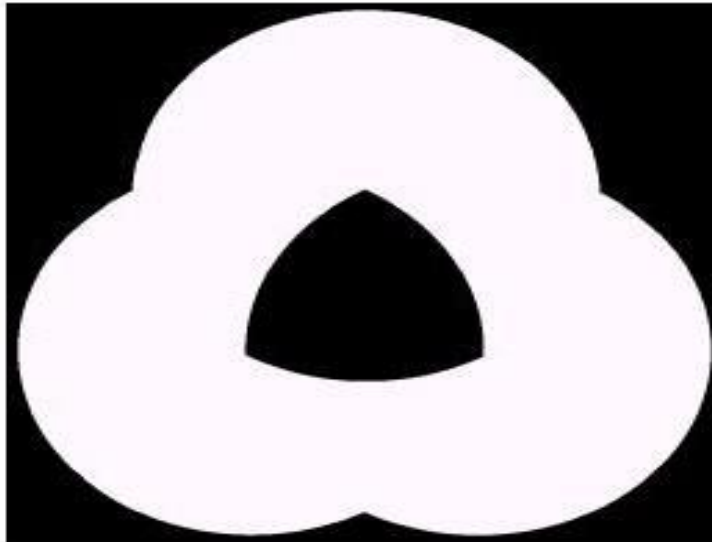
RGB  
Image



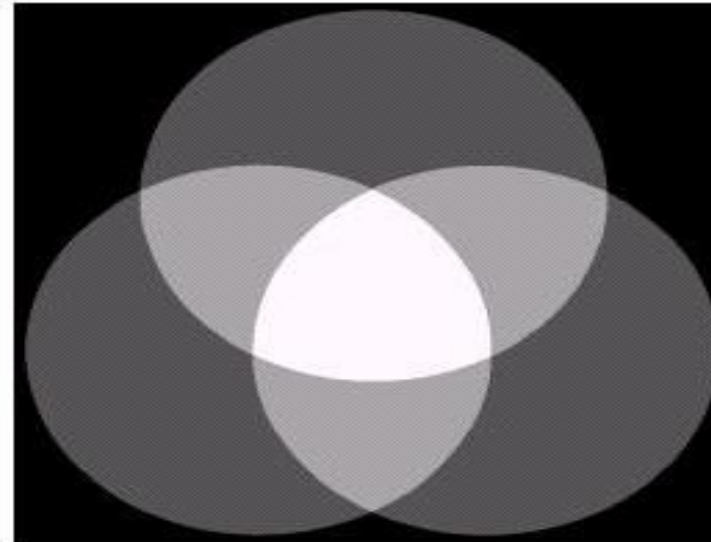
Hue



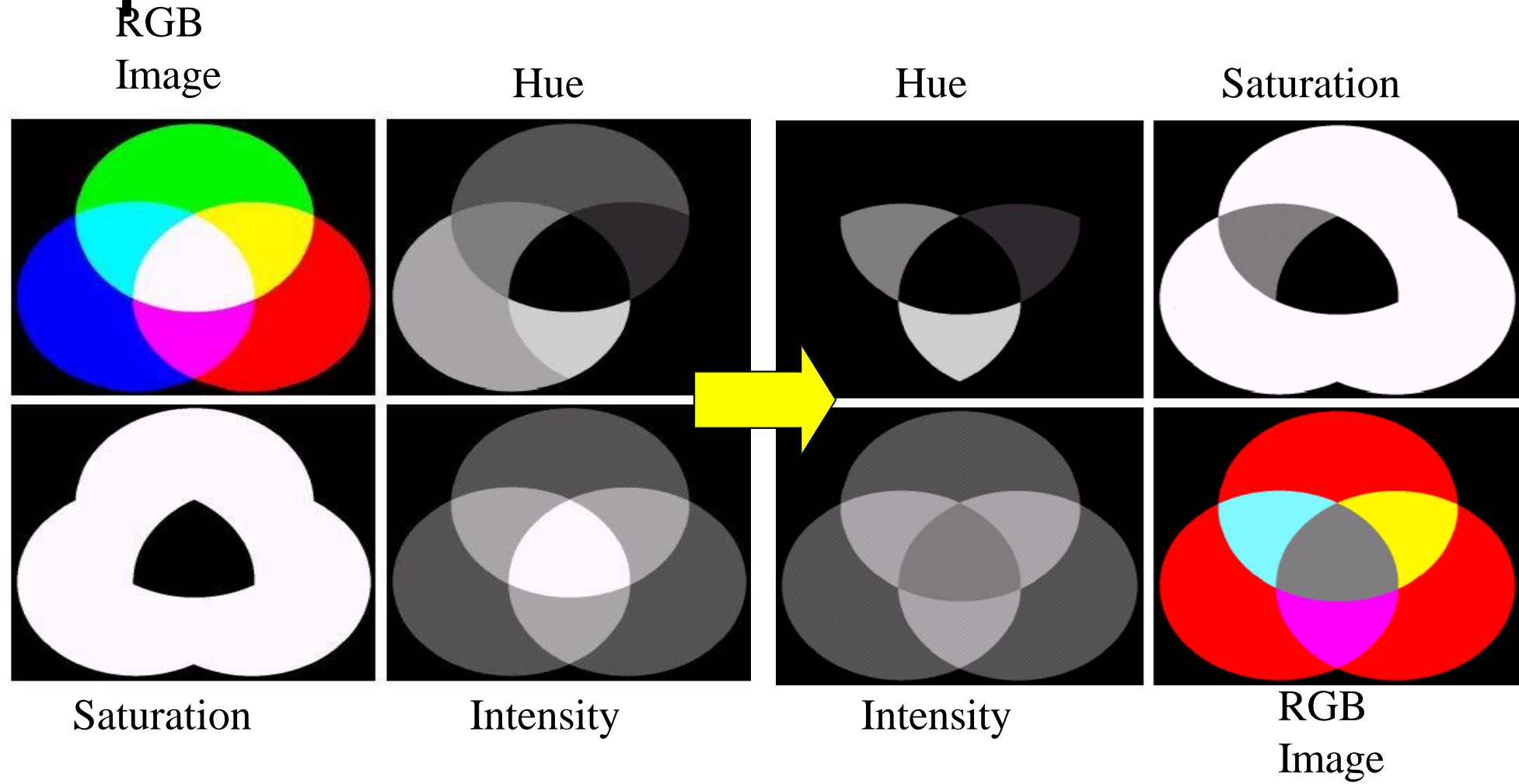
Saturation



Intensity



# Example: Manipulating HSI Components





# Color Coordinates Used in TV Transmission

- Facilitate sending color video via 6MHz mono TV channel
- YIQ for NTSC (National Television Systems Committee) transmission system
  - Use receiver primary system ( $R_N, G_N, B_N$ ) as TV receivers standard
  - Transmission system use (Y, I, Q) color coordinate
    - Y ~ luminance, I & Q ~ chrominance
    - I & Q are transmitted in through orthogonal carriers at the same freq.

$$\begin{bmatrix} Y \\ I \\ Q \end{bmatrix} = \begin{bmatrix} 0.299 & 0.587 & 0.114 \\ 0.596 & -0.275 & -0.321 \\ 0.212 & -0.523 & 0.311 \end{bmatrix} \begin{bmatrix} R_N \\ G_N \\ B_N \end{bmatrix}, \quad \begin{bmatrix} Y \\ U \\ V \end{bmatrix} = \begin{bmatrix} 0.299 & 0.587 & 0.114 \\ -0.147 & -0.289 & 0.436 \\ 0.615 & -0.515 & -0.100 \end{bmatrix} \begin{bmatrix} R_P \\ G_P \\ B_P \end{bmatrix}.$$

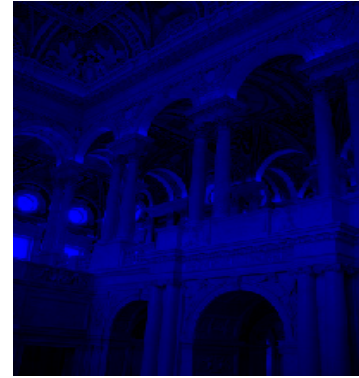
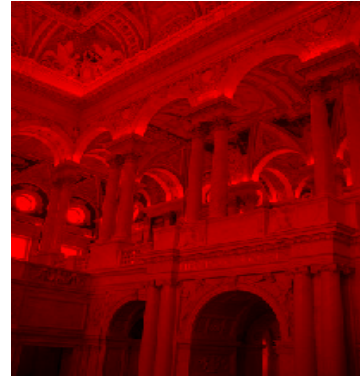
- YUV (YCbCr) for PAL and digital video
  - Y ~ luminance, Cb and Cr ~ chrominance



# Color Coordinates

- RGB of CIE
- XYZ of CIE
- RGB of NTSC
- YIQ of NTSC
- YUV (YCbCr)
- CMY

# Examples



RGB



HSV



YUV

# Examples



A colour image



Red component



Green component



Blue component

RGB



Hue



Saturation

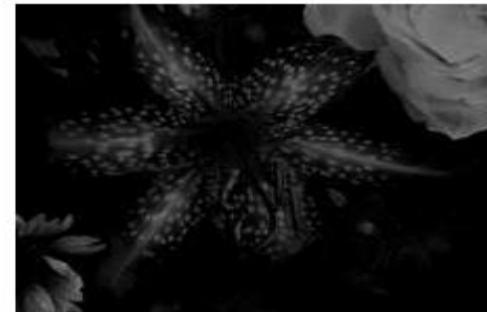


Value

HSV



Y



I



Q

YIQ



# Summary

- Monochrome human vision
  - visual properties: luminance vs. brightness, etc.
  - image fidelity criteria
- Color
  - Color representations and three primary colors
  - Color coordinates



# Color Image Processing

There are 2 types of color image processes

1. Pseudocolor image process: Assigning colors to gray values based on a specific criterion. Gray scale images to be processed may be a single image or multiple images such as multispectral images

2. Full color image process: The process to manipulate real color images such as color photographs.

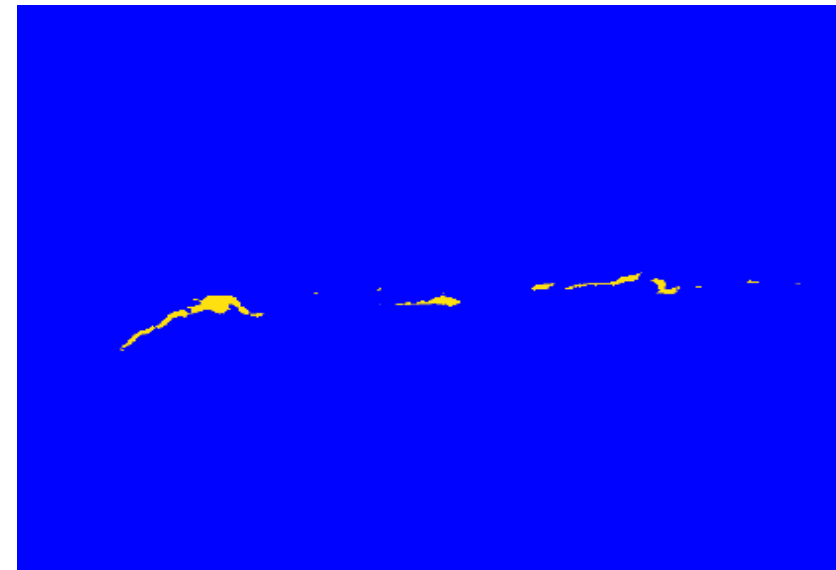
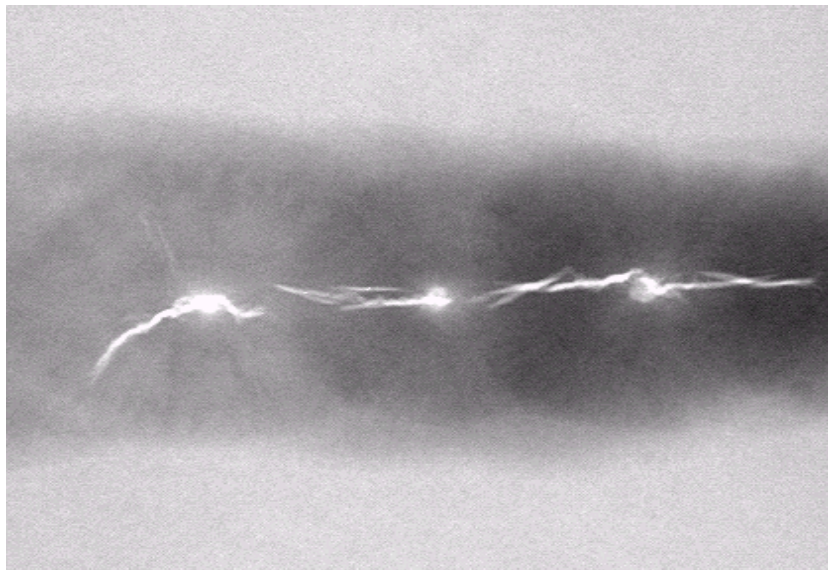


# Pseudocolor Image Processing

Pseudo color = false color : In some case there is no “color” concept for a gray scale image but we can assign “false” colors to an image.

Why we need to assign colors to gray scale image?

Answer: Human can distinguish different colors better than different shades of gray.

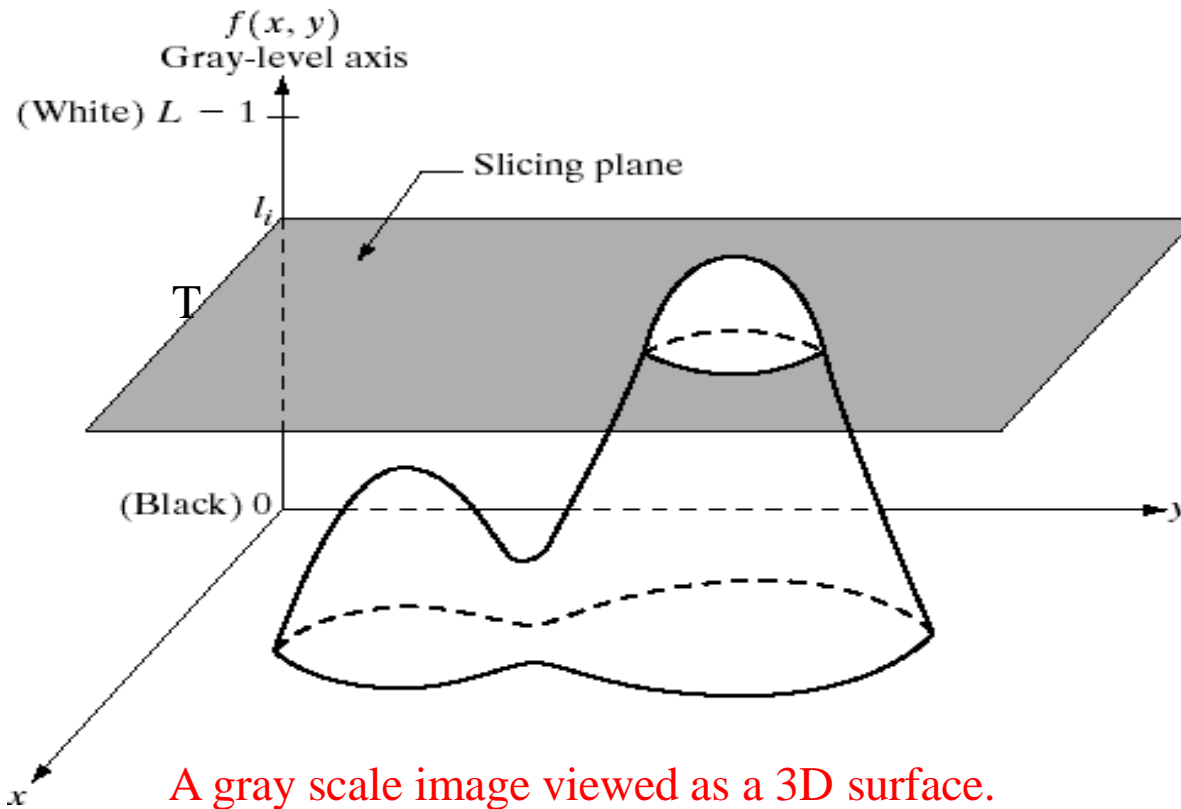


# Intensity Slicing or Density Slicing

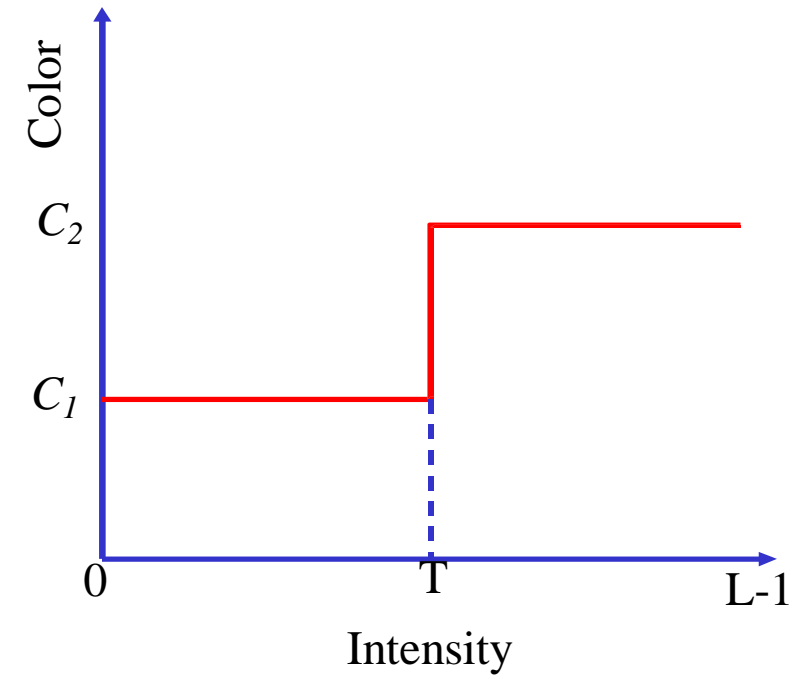
Formula:

$$g(x, y) = \begin{cases} C_1 & \text{if } f(x, y) \leq T \\ C_2 & \text{if } f(x, y) > T \end{cases}$$

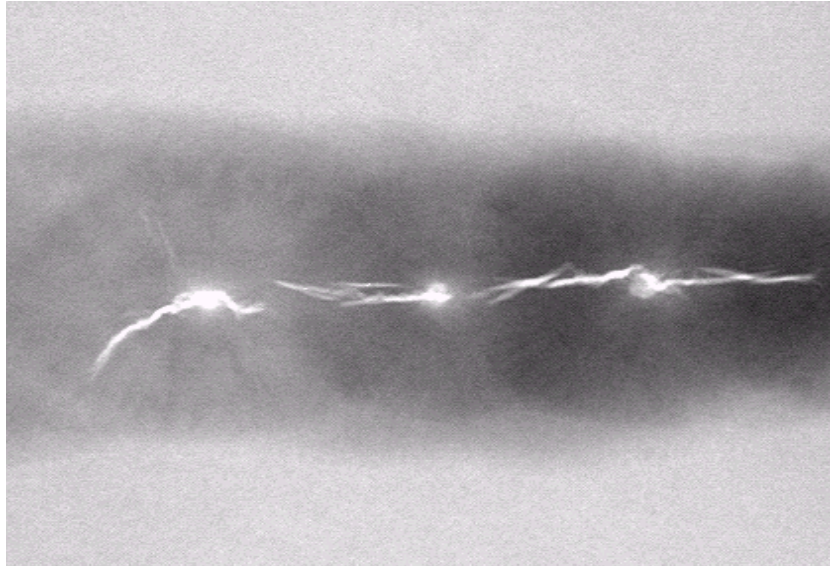
$C_1$  = Color No. 1  
 $C_2$  = Color No. 2



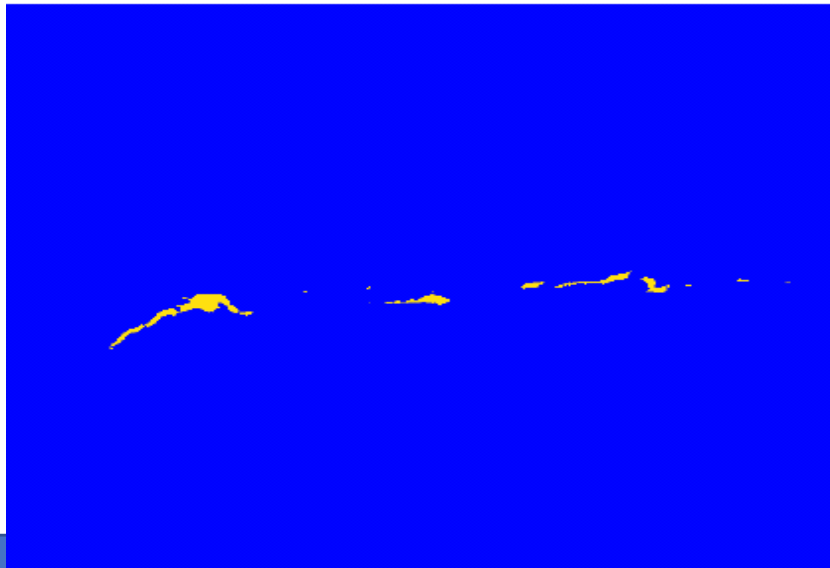
A gray scale image viewed as a 3D surface.



# Intensity Slicing Example



An X-ray image of a weld with cracks



After assigning a yellow color to pixels with value 255 and a blue color to all other pixels.

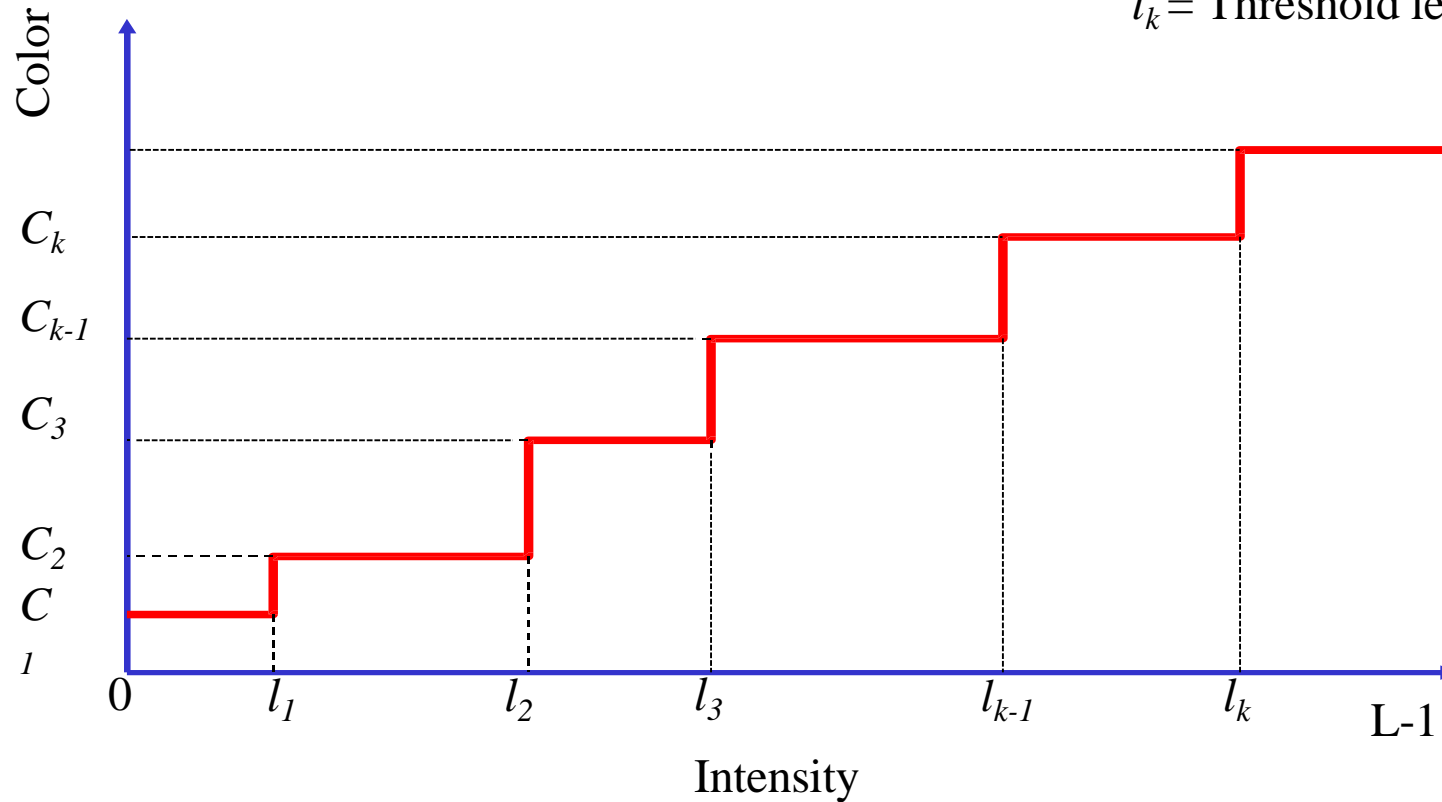


# Multi Level Intensity Slicing

$$g(x, y) = C_k \quad \text{for } l_{k-1} < f(x, y) \leq l_k$$

grey level:	0-63	64-127	128-191	192-255
colour:	blue	magenta	green	red

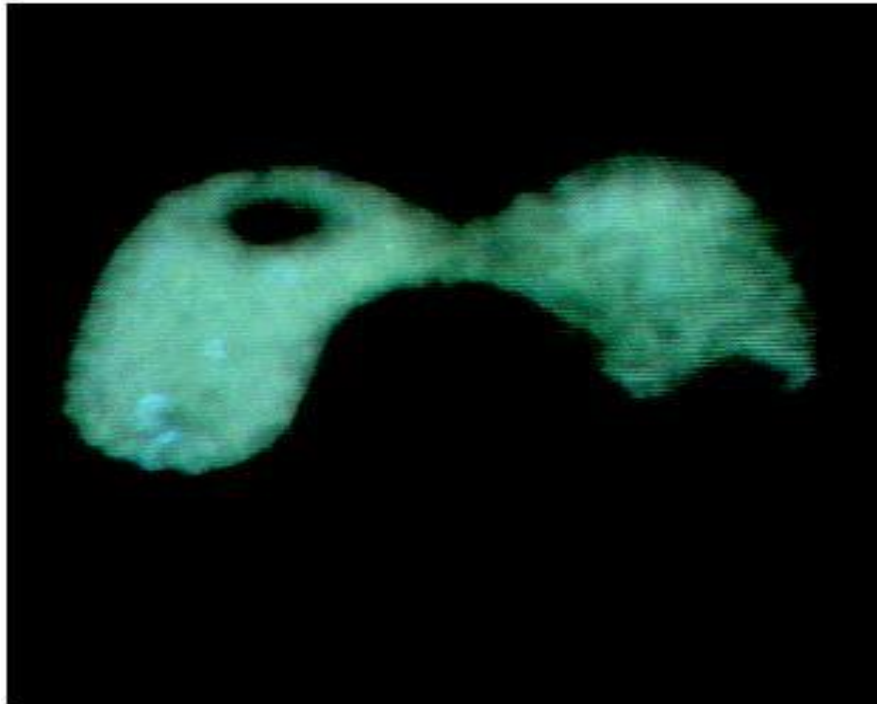
$C_k$  = Color No.  $k$   
 $l_k$  = Threshold level  $k$



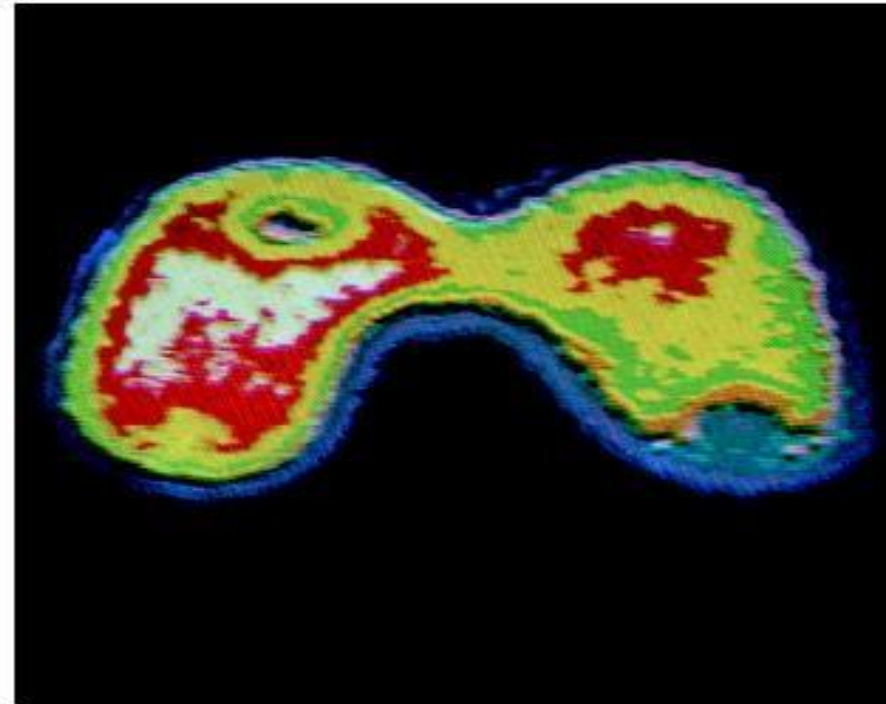
# Multi Level Intensity Slicing Example

$$g(x, y) = C_k \quad \text{for } l_{k-1} < f(x, y) \leq l_k$$

$C_k$  = Color No.  $k$   
 $l_k$  = Threshold level  $k$

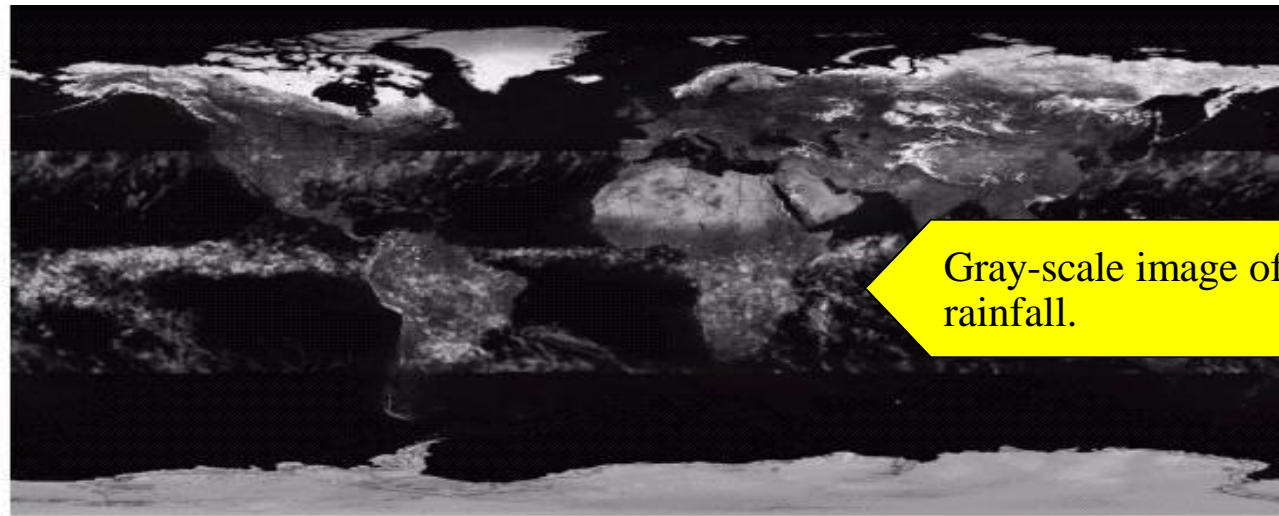


An X-ray image of the Picker Thyroid Phantom.



After density slicing into 8 colors

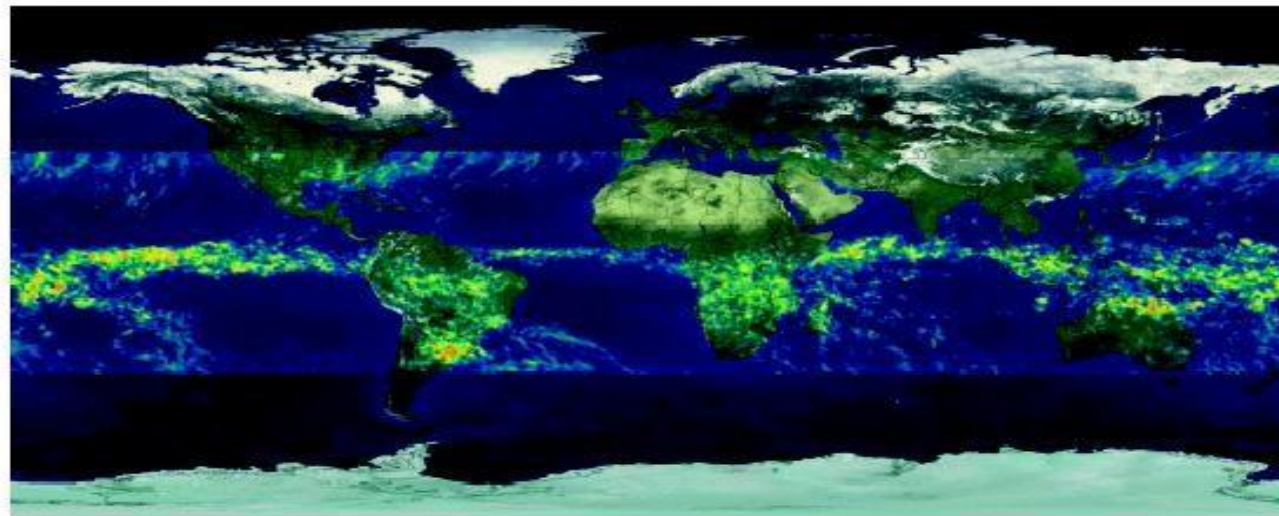
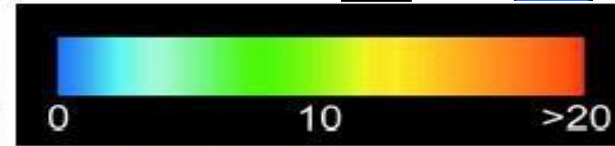
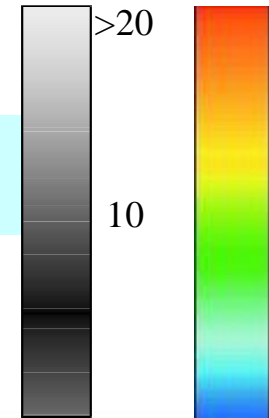
# Color Coding Example



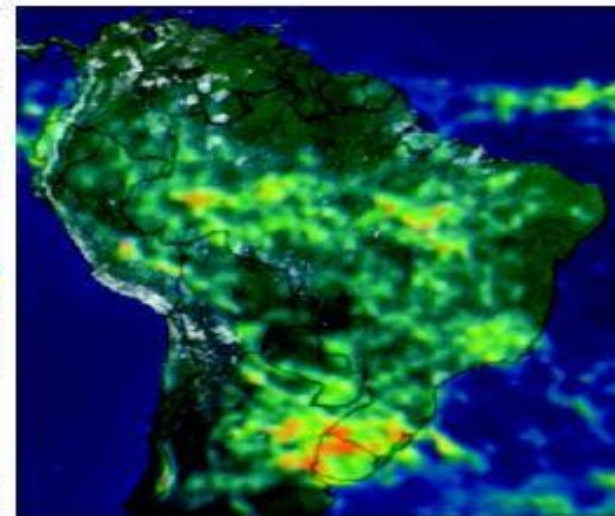
Gray-scale image of average monthly rainfall.

Gray Scale

Color map



Color coded image



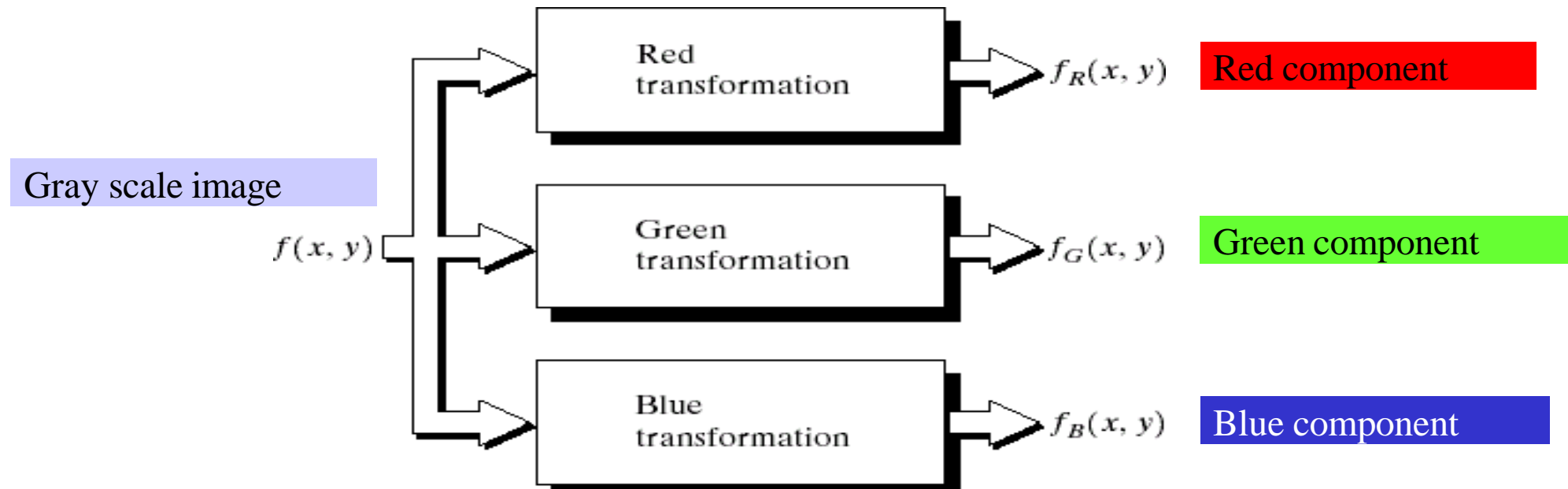
South America region

(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2<sup>nd</sup> Edition.



# Gray Level to Color Transformation

Assigning colors to gray levels based on specific mapping functions



Therefore 3 independent transformations on the intensity of any input pixel is performed.

Then the 3 results are fed separately into the red, green and blue channels of a colour monitor

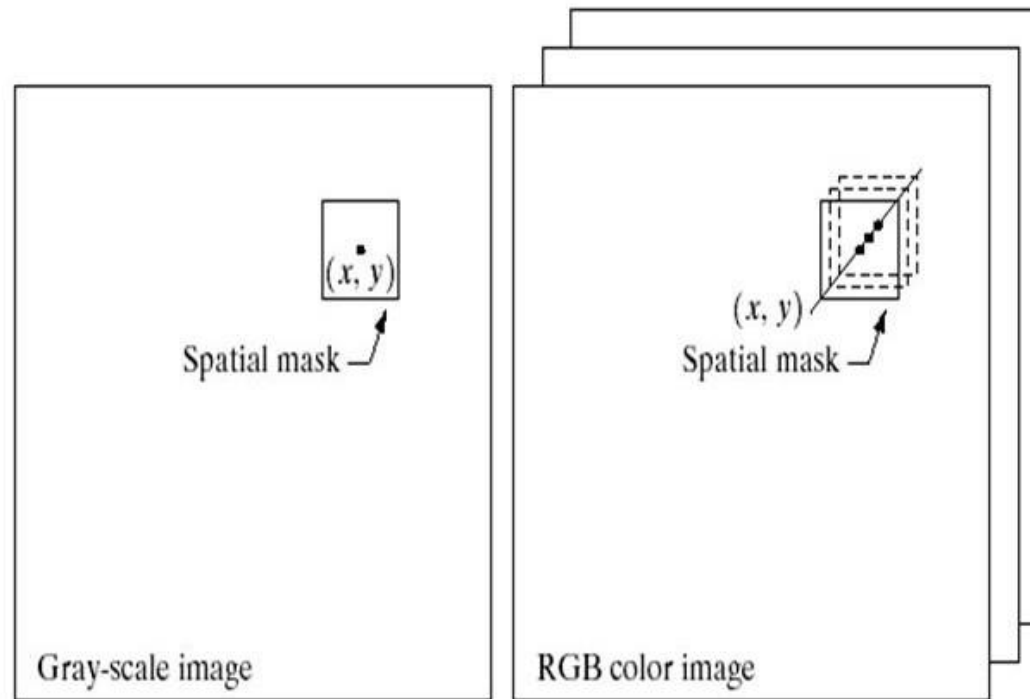
This produces a composite image whose colour content is modulated by the nature of the transformation functions.

They are not functions of position.

# Colour Transformation

a b

**FIGURE 6.29**  
Spatial masks for  
gray-scale and  
RGB color  
images.





# Colour Transformation

- Color transformation can be represented by the expression ::

$$g(x,y) = T[f(x,y)]$$

$f(x,y)$ : input image

$g(x,y)$ : processed (output) image

$T[*]$ : an operator on  $f$  defined over neighborhood of  $(x,y)$ .

The pixel values here are triplets or quartets (i.e group of 3 or 4 values)



# Colour Transformation

- $S_i = T_i(r_1, r_2, \dots, r_n) \quad i = 1, 2, 3, \dots, n$

$r_i$  and  $S_i$  are variables denoting the color components of  $f(x,y)$  and  $g(x,y)$  at any point  $(x,y)$ .

$n$  is the no of color components

$\{T_1, T_2, \dots, T_n\}$  is a set of transformation or color mapping functions.

- Note that  $n$  transformations combine to produce a single transformation  $T$

# Colour Transformation

- The color space chosen determine the value of n.
- If RGB color space is selected then  $n=3$  &  $r_1, r_2, r_3$  denotes the red, blue and green components of the image.
- If CMYK color space is selected then  $n=4$  &  $r_1, r_2, r_3, r_4$  denotes the cyan, hue, magenta and black components of the image.
- Suppose we want to modify the intensity of the given image using  $g(x,y)=k*f(x,y)$  where  $0 < k < 1$



Full color



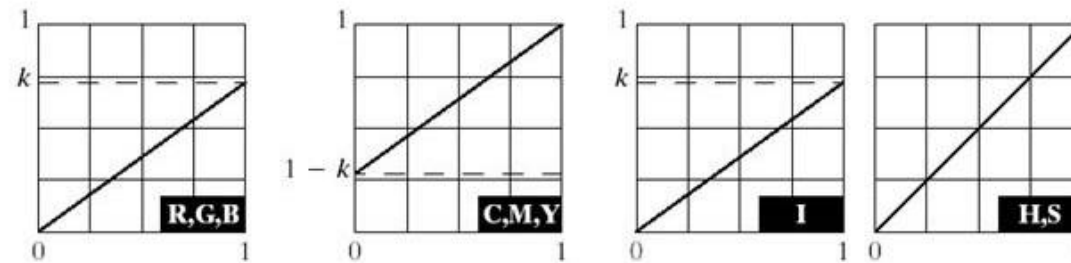
# Colour Transformation

- In HSI color space this can be done with the simple transformation
$$s_3 = k * r_3$$
where  $s_1 = r_1$  and  $s_2 = r_2$   
Only intensity component  $r_3$  is modified.
- In RGB color space 3 components must be transformed:
$$s_i = k * r_i \quad i = 1, 2, 3.$$
- Using  $k = 0.7$  the intensity of an image is decreased by 30%

# Colour Transformation

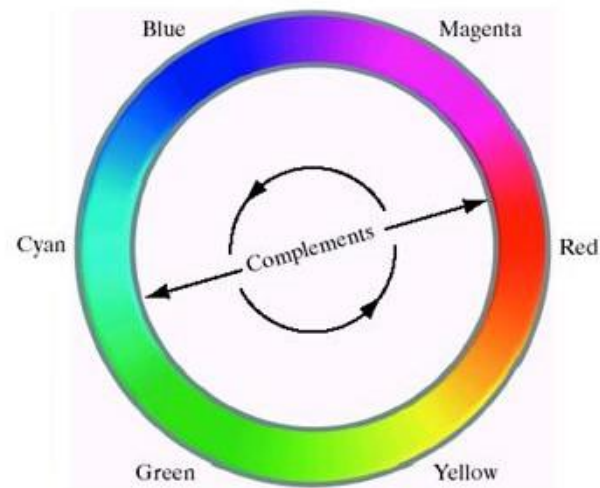
a b  
c d e

**FIGURE 6.31** Adjusting the intensity of an image using color transformations. (a) Original image. (b) Result of decreasing its intensity by 30% (i.e., letting  $k = 0.7$ ). (c)–(e) The required RGB, CMY, and HSI transformation functions. (Original image courtesy of MedData Interactive.)



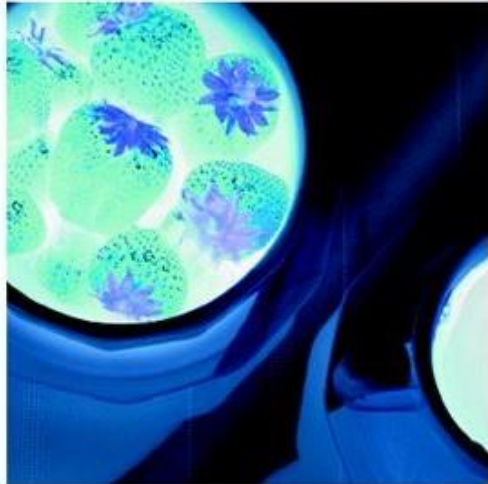
# Colour Complements

- The hues opposite to one another on the Color Circle are called Complements.
- Color Complement transformation is equivalent to image negation in Grayscale images



**FIGURE 6.32**  
Complements on  
the color circle.

# Colour Complements

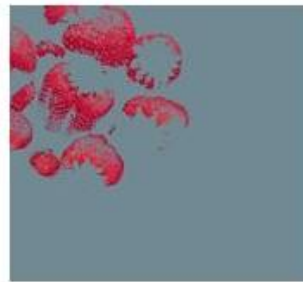


# Colour Slicing

- Highlighting a specific range of colors in an image is useful for separating objects from their surroundings.
- Display the colors of interest so that they are distinguished from background.
- One way to slice a color image is to map the color outside some range of interest to a non prominent neutral color.



Full color





# Colour Image Smoothing

$$\bar{C}(x,y) = \begin{bmatrix} \frac{1}{k} \sum_{(x,y) \in S_{xy}} R(x,y) \\ \frac{1}{k} \sum_{(x,y) \in S_{xy}} G(x,y) \\ \frac{1}{k} \sum_{(x,y) \in S_{xy}} B(x,y) \end{bmatrix}$$

- We recognize the components of this vector as the scalar images that would be obtained by independently smoothing each plane of the starting RGB image using conventional gray scale neighborhood processing.
- Thus we conclude that smoothing by neighborhood averaging can be carried out on a per color plane basis.

# Colour Image Smoothing



a	b
c	d

**FIGURE 6.38**  
(a) RGB image.  
(b) Red component image.  
(c) Green component.  
(d) Blue component.

# Colour Image Smoothing



a b c

**FIGURE 6.40** Image smoothing with a  $5 \times 5$  averaging mask. (a) Result of processing each RGB component image. (b) Result of processing the intensity component of the HSI image and converting to RGB. (c) Difference between the two results.



# Colour Image Smoothing

- Color images can be smoothed in the same way as gray scale images, the difference is that instead of scalar gray level values we must deal with component vectors of the following form:

$$C(x,y) = \begin{pmatrix} C_R(x,y) \\ C_G(x,y) \\ C_B(x,y) \end{pmatrix} = \begin{pmatrix} R(x,y) \\ G(x,y) \\ B(x,y) \end{pmatrix}$$

- The average of the RGB component vector in this neighborhood is:

$$\bar{C}(x,y) = \frac{1}{k} \sum_{(x,y) \in S_{xy}} C(x,y)$$

# Colour Image Sharpening



a b c

**FIGURE 6.41** Image sharpening with the Laplacian. (a) Result of processing each RGB channel. (b) Result of processing the intensity component and converting to RGB. (c) Difference between the two results.



## Chapter 6

# END OF LECTURE